

A-Type K^+ Current Can Act as a Trigger for Bursting in the Absence of a Slow Variable

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Models of bursting in single cells typically include two subsystems with different timescales. Variations in one or more slow variables switch the system between a silent and a spiking state. We have developed a model for bursting in the pituitary lactotroph that does not include any slow variable. The model incorporates fast, noninactivating calcium and potassium currents (the spike-generating mechanism), as well as the fast, inactivating A-type potassium current (I_A). I_A is active only briefly at the beginning of a burst, but this brief impulse of I_A acts as a burst trigger, injecting the spike trajectory close to an unstable steady state. The spiraling of the trajectory away from the steady state produces a period of low-amplitude spiking typical of lactotrophs. Increasing the conductance of A-type potassium current brings the trajectory closer to the unstable steady state, increasing burst duration. However, this also increases interburst interval, and for larger conductance values, all activity stops. To our knowledge, this is the first example of a physiologically based, single-compartmental model of bursting with no slow subsystem.

1 Introduction ---

Bursting, a common pattern of electrical activity in excitable cells, is characterized by brief periods of fast spiking (the active phase) and quiescent

periods (the silent phase). The bursting pattern is usually associated with a higher level of hormone or neurotransmitter secretion (Cazalis, Dayanithi, & Nordmann, 1985; Nunemaker, Straume, DeFazio, & Moenter, 2003; Stojilkovic, Zemkova, & Van Goor, 2005) when compared with continuous spiking patterns. There is evidence that bursting may have important roles in signaling in neurons (Gabbiani, Metzner, Wessel, & Koch, 1996; Lisman, 1997).

Numerous mathematical models of bursting in neural and endocrine cells have been developed (Coombes & Bressloff, 2005). Typically the model can be split into fast and slow subsystems, and bursting oscillations are driven by slow activity-dependent oscillations in the slow variables. The fast subsystem is usually bistable, with a stable steady state coexisting with a stable periodic (spiking) solution. One or more slow variables then switch the system between these attractors (Rinzel, 1985, 1987). The duration of the burst depends on the dynamics of the slow variable(s).

In a recent mathematical model of the pituitary lactotroph, we demonstrated that adding a fast A-type K^+ current can increase secretion (Tabak, Toporikova, Freeman, & Bertram, 2007). This is in spite of the fact that I_A is a hyperpolarizing current and would typically be expected to reduce secretion by hyperpolarizing the membrane. The stimulatory action occurs by converting the spiking pattern to bursting. Surprisingly, we found cases of bursting in which bistability was not present in the fast subsystem. Also, bursting persisted when the only slow variable in the model, the intracellular Ca^{2+} concentration, was held fixed. Figure 1 illustrates the difference between this type of bursting and standard bursting based on bistability and a slow variable. In both panels, slow oscillations of Ca^{2+} occur in parallel with the slow voltage oscillations. Nevertheless, Ca^{2+} plays a different role in each case. In Figure 1A, bursting is terminated if intracellular Ca^{2+} is held constant. This is classic bursting, where the slow changes in Ca^{2+} are driving the bursts. In contrast, for the case shown in Figure 1B, clamping Ca^{2+} does not stop the bursts. This indicates that Ca^{2+} is not driving the bursts but simply follows them. The goal of this work is to analyze the latter type of bursting and contrast its mechanism with the standard bursting mechanisms.

To facilitate the analysis, we removed nonessential elements from the lactotroph model. The slow variable in the original model (Ca^{2+} concentration) is removed, and the original Ca^{2+} -activated K^+ current is treated as a constant conductance current. This results in a simplified model with only three variables, all of which vary on a fast timescale relative to the burst period. We show that bursting can be produced with this model in the absence of a slow variable and analyze the dynamic mechanism for this novel form of bursting.

2 Model

The model is a simplification of a recent model for the electrical activity of the pituitary lactotroph (Tabak et al., 2007). The simplified model

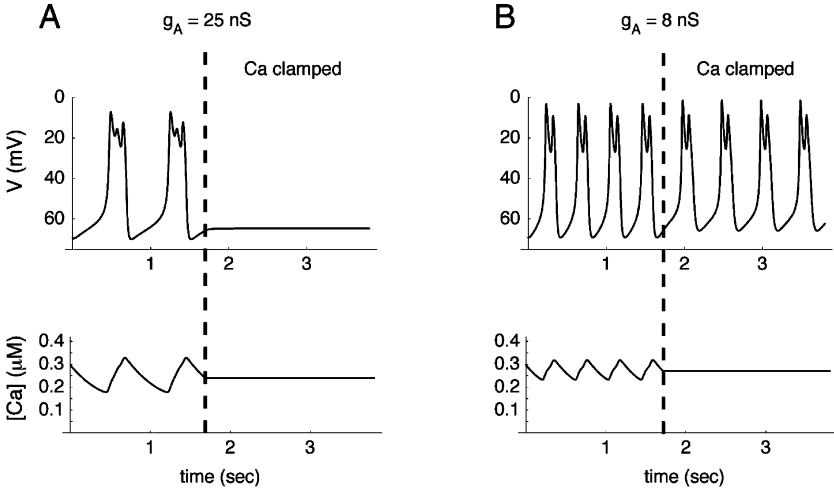


Figure 1: Bursting in a lactotroph model with different A-type current conductances (Tabak et al., 2007). (A) For $g_A = 25 \text{ nS}$, bursting is terminated if intracellular Ca^{2+} is held constant. The bursting mechanism relies on slow variations of Ca^{2+} . (B) For $g_A = 8 \text{ nS}$, clamping Ca^{2+} does not stop the bursts. This indicates an intrinsic bursting mechanism independent of Ca^{2+} .

incorporates three voltage-gated currents: a Ca^{2+} current (I_{Ca}), a delayed rectifier K^+ current (I_{DR}), and a fast and transient A-type K^+ current (I_A). There is also a non-voltage-gated leak current I_L . The dynamics of the three variables V (membrane potential), n (activation of I_{DR}), and e (inactivation of I_A) are described by:

$$C \frac{dV}{dt} = -(I_{Ca} + I_{DR} + I_A + I_L) \quad (2.1)$$

$$\tau_n \frac{dn}{dt} = n_\infty(V) - n \quad (2.2)$$

$$\tau_e \frac{de}{dt} = e_\infty(V) - e. \quad (2.3)$$

The ionic currents are given by

$$I_{Ca} = g_{Ca} m_\infty (V - V_{Ca}) \quad (2.4)$$

$$I_{DR} = g_{DR} n (V - V_K) \quad (2.5)$$

$$I_A = g_A a_\infty e (V - V_K) \quad (2.6)$$

$$I_L = g_L (V - V_K), \quad (2.7)$$

Table 1: Parameter Values.

Parameter	Value	Definition
C	10 pF	Membrane capacitance
g_{Ca}	2 nS	Maximal conductance of Ca^{2+} channels
V_{Ca}	50 mV	Reversal potential for Ca^{2+}
v_m	-20 mV	Voltage value at midpoint of m_∞
s_m	12 mV	Slope parameter of m_∞
g_{DR}	4.4 nS	Maximal conductance of DR K^+ channels
V_K	-75 mV	Reversal potential for K^+
v_n	-5 mV	Voltage value at midpoint of n_∞
s_n	10 mV	Slope parameter of n_∞
τ_n	43 ms	Time constant of n
g_A	0-20 nS	Maximal conductance of A channels
v_a	-20 mV	Voltage value at midpoint of a_∞
s_a	10 mV	Slope parameter of a_∞
v_e	-60 mV	Voltage value at midpoint of e_∞
s_e	5 mV	Slope parameter of e_∞
g_L	0.3 nS	Maximal conductance of leak current
τ_e	20 ms	Time constant of e

and the steady-state activation functions have the form

$$x_\infty = \frac{1}{1 + \exp\left(\frac{V_x - V}{s_x}\right)}, \quad (2.8)$$

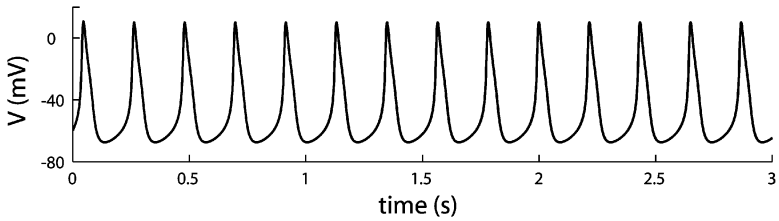
where x represents an activation variable (m , n , and a). The inactivation steady-state function is

$$e_\infty = \frac{1}{1 + \exp\left(\frac{V - V_e}{s_e}\right)}. \quad (2.9)$$

When I_A is not present ($g_A = 0$), the model has the form of the Morris-Lecar model (Morris & Lecar, 1981).

Parameter values are given in Table 1. Values of the kinetic parameters for I_{Ca} were obtained from Lledo, Legendre, Israel, and Vincent (1990), and the values for I_{DR} and I_A are based on Herrington and Lingle (1994). Equations were integrated, and bifurcation diagrams were constructed, using the software package XPPAUT (Ermentrout, 2002). The fourth-order Runge-Kutta integration method was used, with a time step of 0.5 ms. Reducing the time step had no effect on the simulations. The code for this model is freely available online at www.math.fsu.edu/bertram/software/pituitary.

A



B

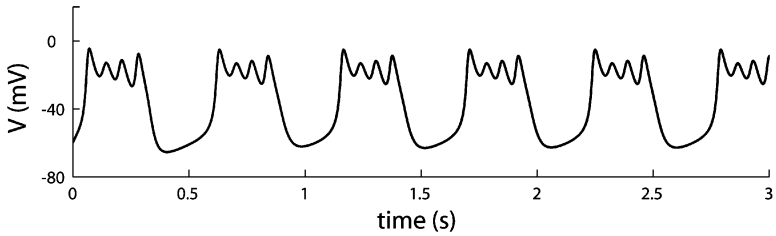


Figure 2: I_A converts spiking to bursting. (A) For $g_A = 0$ nS, the model cell is spiking. (B) Increasing the A-type K^+ channel conductance to $g_A = 13$ nS converts spiking to bursting.

3 Results

3.1 I_A Converts Spiking into Bursting. In our recent model of the pituitary lactotroph we found that adding a small amount of A-type K^+ current converts the model cell from a spiker to a burster (Tabak et al., 2007). Figure 2 illustrates the effect of increasing g_A from 0 to 13 nS in the reduced lactotroph model. For $g_A = 0$ (see Figure 2A), the model cell is spiking. When g_A is increased to 13 nS (see Figure 2B), the spiking is converted into bursting. The duration of the burst, approximately 600 ms, is much larger than the time constants of all model variables ($\tau_n = 43$ ms, $\tau_e = 20$ ms and the membrane time constant is 33 ms).

Rush and Rinzel (1995) also obtained a switch to bursting by adding an A current to a spiking model. In their case, though, the inactivation variable of the A current acted as a slow variable, switching the fast subsystem between a high (oscillatory) state and a low, stable state. To demonstrate that this is not the case in our model, we plot in Figure 3 the bifurcation diagram of the V - n subsystem with e treated as a parameter. For $e = 0$, the system has a single unstable steady state surrounded by a stable limit cycle. As e is increased, the steady state becomes stable through a subcritical Hopf bifurcation (HB). The periodic branch born at the Hopf bifurcation emerges as unstable but gains stability at a saddle node of periodics (SNP)

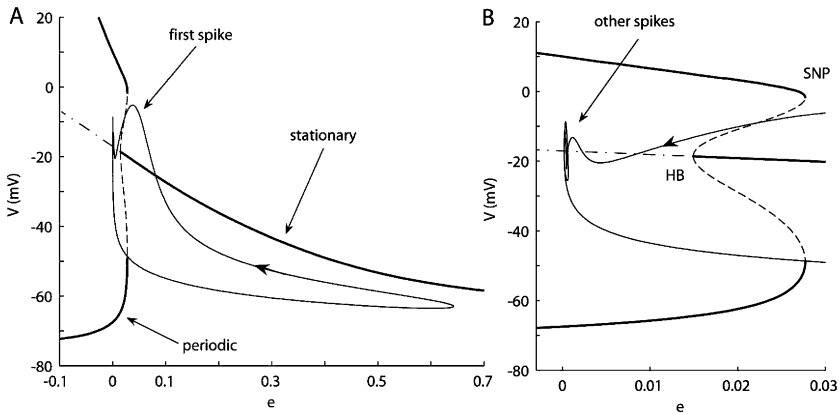


Figure 3: (A) Bifurcation diagram of the V - n subsystem with inactivation variable e treated as a parameter ($g_A = 13$ nS). Thick lines represent stable solutions, and thin lines represent unstable ones. The maximum and minimum of the periodic solution are shown as upper and lower periodic branches, respectively. The projection of the burst trajectory of the full system is superimposed, and does not follow the bifurcation diagram of the V - n subsystem. (B) The same for the smaller range of e . Most of the active phase of the burst occurs near $e = 0$. HB: Hopf bifurcation. SNP: saddle node periodic bifurcation.

bifurcation. Between the HB and SNP bifurcations is a region of bistability, with coexisting stable steady state and periodic solutions. However, the burst trajectory (superimposed) does not utilize this bistability region, and indeed does not follow the bifurcation diagram of the V - n subsystem. The spikes of the active phase occur for low values of e , and indeed it is clear from Figure 3B that e is nearly zero during the most of the active phase; therefore, variations of e do not terminate the burst. Together, these observations indicate that the bursting shown in Figure 2B cannot be described using fast-slow analysis with e as the slow variable.

3.2 I_A Acts as a Burst Trigger. To investigate the mechanism of burst generation, we plot the two potassium currents of the model, I_{DR} and I_A , during one full burst cycle. I_{DR} reflects the burst trajectory. I_A is near zero during most of the active phase, peaking at the onset of the burst (see Figure 4). Is the entire I_A impulse necessary for bursting? To address this question, we blocked I_A at different time points during the burst. In Figure 5A we blocked I_A (set $g_A = 0$) after 80 ms, which is midway along the downstroke of the impulse. As a result, the burst is totally eliminated, and only a single large-amplitude spike is produced. Note also that when I_A is blocked, subsequent bursts do not occur.

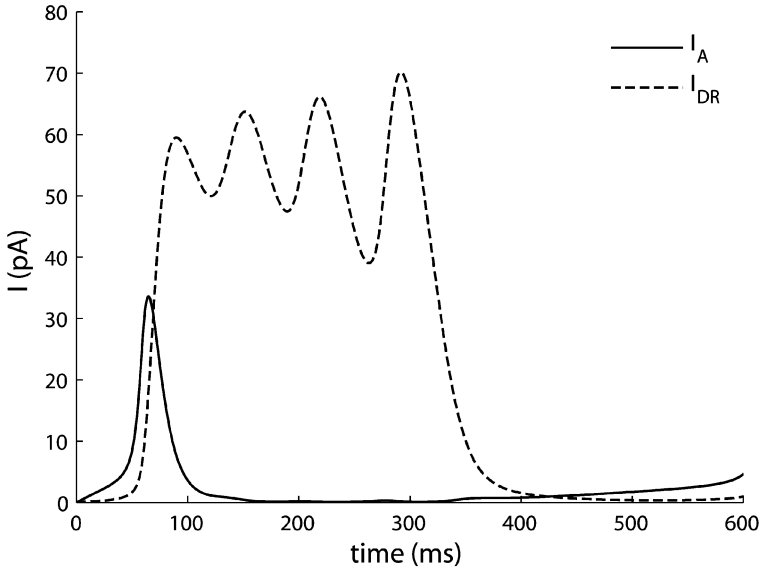


Figure 4: Two K^+ currents during one full burst cycle ($g_A = 13$ nS). There is an impulse in I_A at the beginning of the burst, and I_A is near zero during the remainder of the active phase.

Thus, a nearly complete I_A impulse is necessary to induce bursting, but is it sufficient? If we block I_A only 7 ms later, at 87 ms (see Figure 5B), then the burst appears, but it is short, with only 2 spikes per burst. If I_A is blocked at 90 ms (see Figure 5C), when the I_A impulse is almost complete, the burst is complete. That is, the burst has the same length as the control burst in Figure 4. Thus, the I_A impulse alone is sufficient to induce bursting; I_A can be set to zero throughout the remainder of the burst, and the burst will proceed. Therefore, the I_A impulse acts as a trigger for bursting.

How does the I_A impulse trigger the burst? To address this question, we view the burst trajectory in the V - n - I_A space. Figures 6A to 6C correspond to the I_A current profiles of Figures 5A to 5C. Figure 6D shows the trajectory without any block of I_A (current profile in Figure 4).

When $g_A = 0$ the system spikes, and the spiking trajectory is in the V - n plane, surrounding an unstable steady state. This spiking trajectory is shown in gray in Figure 6D. When $g_A = 13$ nS (see Figure 6A), the trajectory leaves the V - n plane during the I_A impulse. Blocking I_A at 80 ms returns the trajectory to the V - n plane, where it approaches the spiking limit cycle around the unstable steady state (open circle).

When I_A is blocked later, at 87 ms, the trajectory reenters the V - n plane closer to the unstable steady state and spirals around it twice before approaching the spiking limit cycle (see Figure 6B). Each spiral is a

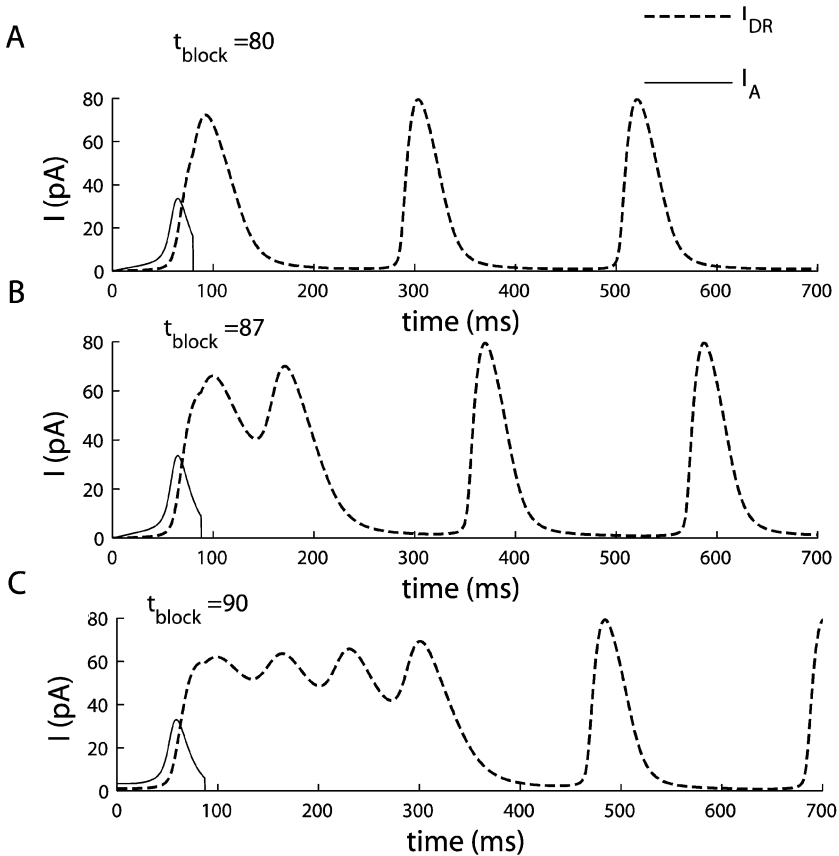


Figure 5: The effect of blocking I_A at different time points. (A) I_A blocked at 80 ms eliminates the burst. (B) I_A blocked at 87 ms reduces the burst to two spikes. (C) I_A blocked at 90 ms results in a complete burst. Before the block, $g_A = 13$ nS.

low-amplitude electrical impulse during the active phase of the burst (see Figure 5B). If I_A is blocked later, at 90 ms, the trajectory reenters even closer to the unstable steady state (see Figure 6C). As a result, more spirals occur before the trajectory moves out toward the spiking limit cycle. This produces a burst with more low-amplitude spikes (see Figure 5C). When I_A is not blocked, the trajectory enters the V - n plane near the unstable steady state at the end of the I_A impulse (see Figure 6D). The remainder of the burst takes place in the V - n plane, so I_A plays no role after the impulse.

3.3 Increase in I_A Increases Burst Duration. Not only does the I_A impulse trigger the burst, but its magnitude determines the burst length. In

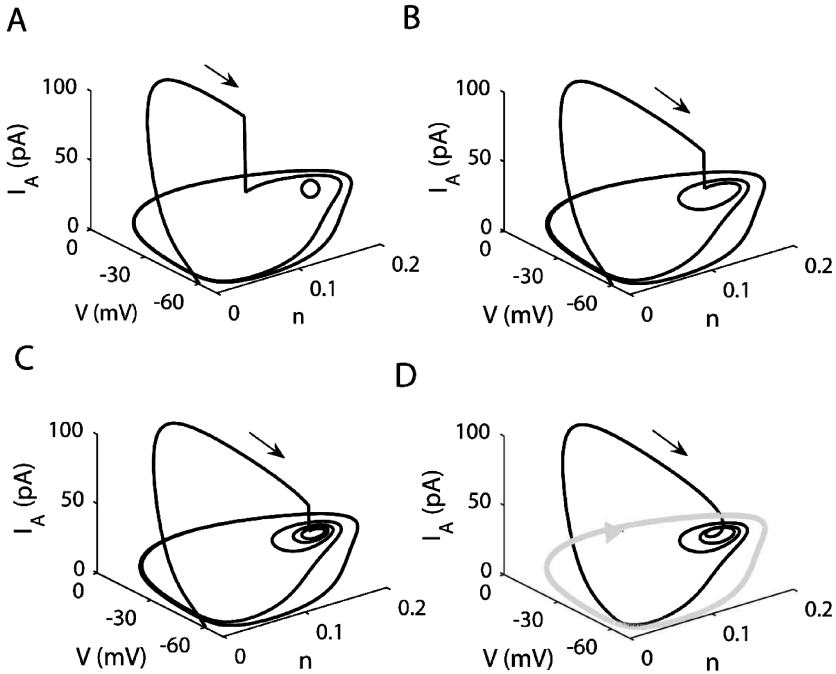


Figure 6: The effect of I_A block shown in the V - n - I_A space. (A) I_A blocked at 80 ms. The open circle in the V - n plane represents the unstable steady state. (B) I_A blocked at 87 ms. (C) I_A blocked at 90 ms. (D) Trajectory with unblocked I_A ($g_A = 13$ nS). The gray curve represents the continuous spiking limit cycle ($g_A = 0$).

Figure 7A, g_A is increased from 0 to 23 nS in steps. When g_A is increased to 3 nS, the spiking pattern switches to a two-spike burst. Another spike is added when g_A is increased to 7 nS. Increasing g_A to 13 nS adds a fourth spike to the burst, and so on. There are also more complex spiking patterns between the regular n -spike bursts. We found chaotic patterns between the two- and three-spike bursts, three- and four-spike bursts, as well as between the four- and five-spike patterns (see Figure 7C). Further increase of g_A , larger than 20.85 nS, stops all activity.

Figure 7B shows the bifurcation diagram of the V - e subsystem with n treated as a parameter for different values of g_A . The n -nullcline is also shown. The lower and upper branches of the z-shaped bifurcation diagram consist of stable equilibria of the V - e subsystem, while equilibria on the middle branch are unstable. For lower values of g_A ($g_A = 0$ and $g_A = 7$ nS), there is a single depolarized unstable steady state of the full V - e - n system. Increasing g_A stretches the bifurcation diagram so that the lower

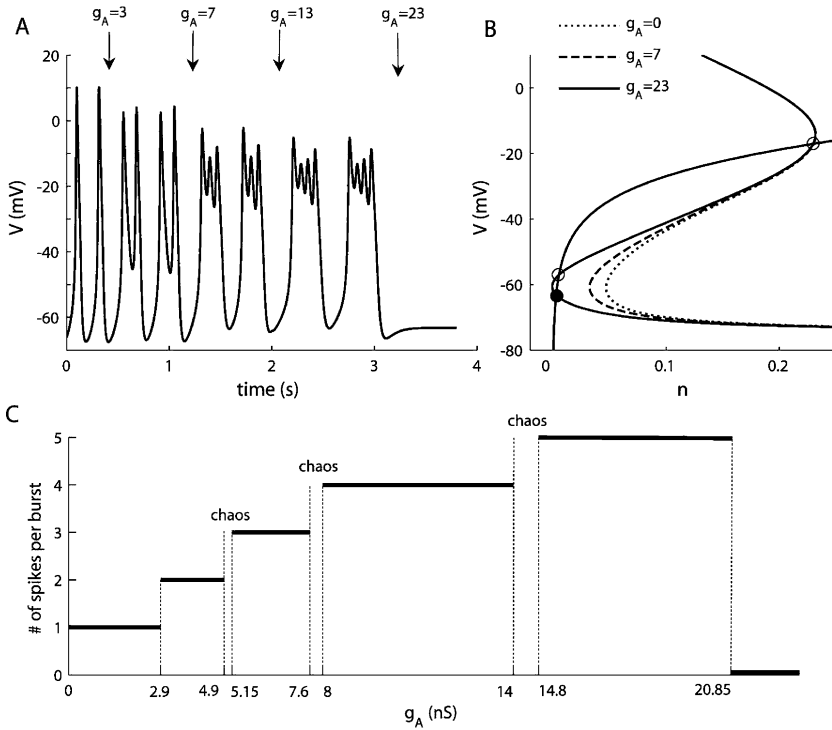


Figure 7: (A) Increasing g_A increases the number of spikes per burst until activity stops. (B) Bifurcation diagram for the V - n subsystem with n treated as a parameter. $g_A = 0$ (dotted line), $g_A = 7$ nS (dashed line), and $g_A = 23$ nS (solid line). The n -nullcline is also shown. Open circles represent unstable steady states, and the closed circle denotes a stable steady state. (C) Number of spikes per burst as function of g_A . The chaotic bursting regions are between the dashed lines.

knee moves to the left. When $g_A = 23$ nS, the lower knee intersects the n -nullcline, and two new steady states appear, one of which is stable. The trajectory is now attracted to this lower stable steady state, and bursting stops.

To explain how the burst increases in length with an increase in g_A , we project the burst trajectory onto the V - n plane. Figure 8A shows the superimposed trajectories with $g_A = 0$ and $g_A = 3$ nS. The dashed curve is the spiking trajectory when $g_A = 0$. The unstable steady state (open circle) is the intersection of the V and n nullclines (dot-dashed curves). When g_A is increased to 3 nS (solid curve), the rapidly activating hyperpolarizing current reduces the rise in voltage during the upstroke of the spike (arrow), so the trajectory comes closer to the unstable spiral. Movement around

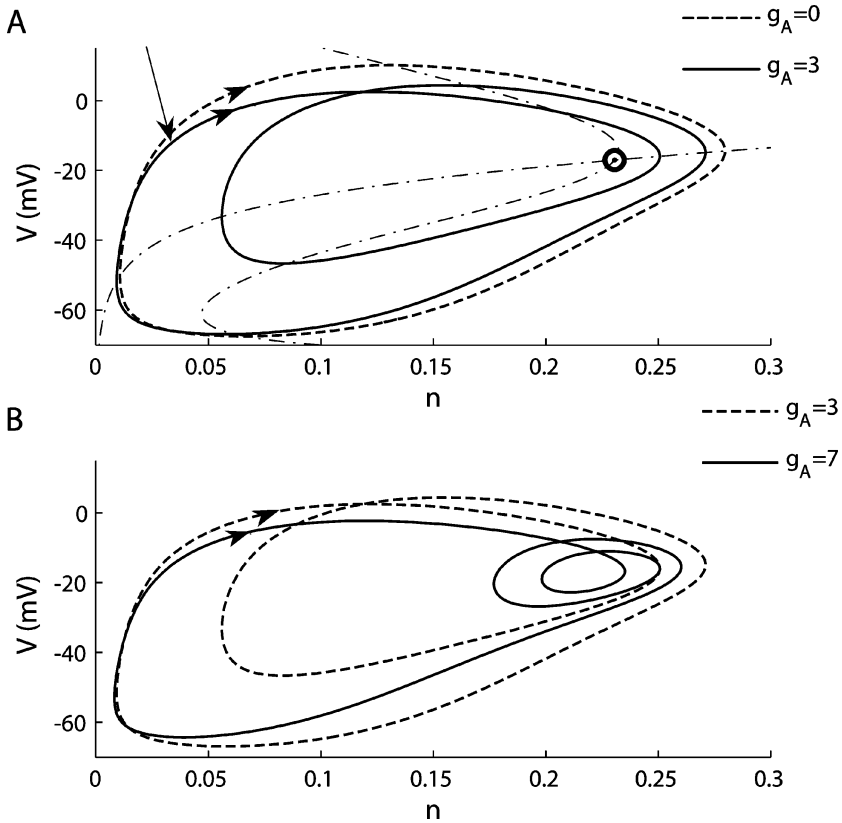


Figure 8: Mechanism by which increasing the I_A impulse magnitude increases the burst duration. (A) Trajectories projected onto the V - n plane with $g_A = 0$ nS (dashed line) and $g_A = 3$ nS (solid line). The dot-dashed lines are the V and n nullclines for $g_A = 0$. The arrow indicates the beginning of the spike upstroke, and the open circle is an unstable steady state. (B) The V - n phase plane for $g_A = 3$ nS (dashed line) and $g_A = 7$ nS (solid line). The increase in g_A moves the trajectory closer to the unstable steady state, producing more spikes per burst.

this spiral produces a burst with two spikes. For larger I_A ($g_A = 7$ nS), the trajectory has a closer approach to the unstable spiral (see Figure 8B), making three turns around it before entering the silent phase of the burst. Thus, a larger I_A moves the trajectory closer to the unstable spiral, creating a longer active phase of the burst. Note that the number of revolutions around the unstable spiral is highly sensitive to the way that the trajectory approaches the spiral at the beginning of the burst. Thus, chaotic spiking patterns can be produced, as mentioned above.

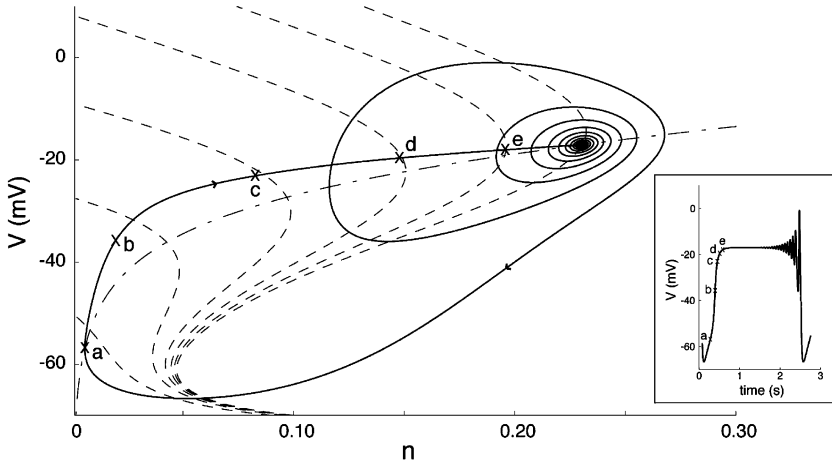


Figure 9: Bending of the trajectory in V - n space for $\tau_e = 80$ ms. Points a–e correspond to values of e of 0.5, 0.2, 0.1, 0.05, and 0.02. For each of these points, the corresponding V -nullcline of the V - n subsystem is represented (dashed z-shaped curve), as is the n -nullcline (dot-dashed). As V increases, e decreases, moving the V -nullcline upward and to the right. The intersections of the n -nullcline and the V -nullclines corresponding to points a–e are steady states of the V - n subsystem, not of the V - n - e system. Only the intersection for $e = 0$ defines a steady state of the full system. Inset: Time course of membrane potential during one “burst.” Most of the burst period is spent in the active phase where $e \approx 0$.

3.4 How Is the Trajectory Driven Toward an Unstable Steady State? The previous results show that by turning on at the beginning of a burst, I_A pushes the trajectory toward the unstable steady state of the V - n subsystem. For larger I_A , the trajectory passes closer to that unstable steady state. How can I_A bring the trajectory so close to a repellent state? As shown in Figure 3, the steady state of the V - n subsystem becomes stable when e increases above its value at the Hopf bifurcation (~ 0.02). At the beginning of a burst, before I_A is fully inactivated, this stable steady state can behave as an attractor and thus bend the trajectory as shown above, before becoming unstable as e reaches 0.

This is shown in Figure 9. Although e is not a slow variable, we have slowed it (τ_e increased fourfold to 80 ms) to better demonstrate the effect, as Drover, Rubin, Su, & Ermentrout (2004) did. The figure shows the trajectory of the system projected in the V - n plane. Five points (a–e) along the trajectory at the onset of a burst are represented. They correspond to values of e of 0.5, 0.2, 0.1, 0.05, and 0.02. For each of these points, the corresponding V -nullcline of the V - n subsystem is shown (z-shaped, dashed). The intersection of each V -nullcline and the n -nullcline (dot-dashed curve)

is a stable steady state of the V - n subsystem for the corresponding e and a pseudo steady state for the full system. Thus, if e were frozen when the trajectory is at point a , it would be attracted to the stable steady state just above a . However e decreases, so the z -shaped curve moves up and to the right, and so does the attracting steady state. The trajectory thus never reaches any of the pseudo steady states, but it is bent while tracking these moving targets. When e is near zero, the steady state becomes unstable, but only weakly so. Thus, the trajectory spirals away, but slowly. A similar situation occurs when e is not slowed, but then the z -shaped curves move faster, so the trajectory is less affected and does not come as close to the unstable steady state as I_A fully inactivates.

Figure 9 illustrates the fundamental difference between standard bursting (i.e., square wave bursting) and the bursting presented here. In standard bursting, a slow variable slowly takes the system to transition points where activity abruptly switches between high (oscillatory) and low (stationary) states. In our model, a fast variable quickly moves the only steady state of the V - n subsystem between a high, unstable position to a series of low, stable positions, thus creating the different phases of the burst.

Finally, this highlights the two characteristics of I_A needed to produce this type of bursting. First, I_A needs to activate quickly, so that the unstable steady state of the V - n subsystem can become attracting. Second, it needs to inactivate; otherwise, the system would remain indefinitely in that steady state.

4 Discussion

We have shown a new mechanism for bursting in a simplified excitable cell model. In classical bursters, the system can be split into fast and slow subsystems, and bursting oscillations are driven by slow activity-dependent oscillations in the slow variables. The fast subsystem is usually bistable, with a stable steady state coexisting with a stable periodic (spiking) solution. One or more slow variables then switch the system between these attractors. Unlike classical bursting, the bursting that we describe is produced without a slow variable. An A-type K^+ current converts the spiking pattern to bursting by injecting the trajectory to a location near an unstable spiral. Motion around the spiral creates low-amplitude spikes riding on a voltage plateau, similar to what is observed in pituitary lactotrophs (Oxford & Tse, 1993; Van Goor, Zivadinovic, Martinez-Fuentes, & Stojilkovic, 2001), somatotrophs (Van Goor, Li, & Stojilkovic, 2001), corticotrophs (Kuryshv, Childs, & Ritchie, 1996; Kuryshv, Haak, Childs, & Ritchie, 1997), and clonal pituitary cells (Adler et al., 1983). I_A also plays its traditional role of slowing the next occurrence of an impulse, contributing to the silent phase duration between the bursts.

The A-type potassium current is widely known to delay spiking or reduce firing frequency (Connor, Walter, & McKown, 1977). It has been shown

that changes in this current's conductance and dynamic properties can result in bursting (Rush & Rinzel, 1995). However, in the Rush-Rinzel model, the A-current inactivation acts as a slow variable to terminate the burst. This is a classic fast-slow system, with the I_A inactivation variable accumulating during the burst. The hyperpolarization following each spike decreases the inactivation of I_A until the current becomes large enough to terminate the burst. Thus, increasing g_A decreases the burst duration. In our model, I_A does not terminate the burst since it quickly inactivates and no deinactivation occurs during the burst since the model cell stays depolarized until the end of the burst. Also, in our model, increasing g_A increases the burst duration, although if g_A is too large, the bursting is terminated altogether, and the model cell becomes silent. Thus, the transition sequence from tonic spiking to bursting to quiescence as g_A is increased in our model differs from the sequence in the square-wave burster of Rush and Rinzel.

Another example of bursting driven by a slowly inactivated K^+ current is a model of pyramidal cells in the electrosensory lateral lobe of weakly electric fish (Doiron, Laing, Longtin, & Maler, 2002). This is a two-compartment model, with impulse propagation between the soma and an active dendrite. Like the Rush and Rinzel model, this "ghostbuster" model has two timescales. The single slow variable is the K^+ current inactivation in the dendrite, which accumulates during the burst. The soma begins to spike, and the spike is transmitted to the dendrite and back again to the soma. As this Ping-Pong effect continues, the K^+ current in the dendrite inactivates. This speeds up the spiking, so that eventually the soma spikes so fast that the dendrite cannot keep up. The lack of a dendritic spike then terminates the burst. Thus, in contrast to the model of Rush and Rinzel, it is the accumulation of inactivation, not deinactivation, that terminates the bursting. In our model, however, there is no slowly accumulating process.

The A-type K^+ current has been used in a wide variety of excitable cell models (Connor, Walter, & McKown, 1977; Gerber & Jakobsson, 1993; Rybak, Paton, & Schwaber, 1997; Wustenberg et al., 2004). However, there are no examples of I_A inducing bursting of the nature described here. Why does this happen in our model? The physiological set of parameters used in the lactotroph model puts the unstable steady state at a depolarized value. This is just below the upper branch of the z-shaped bifurcation diagram (see Figure 7B). Had the intersection been on the upper branch, the steady state would have been stable. Thus, the unstable steady state is only weakly repelling, so that the trajectory spirals several times before leaving the neighborhood of the steady state. If the steady state had occurred lower on the bifurcation diagram (e.g., by shifting I_{DR} activation to lower V), the steady state would be more repelling, and it would require more I_A current to bend the trajectory toward the steady state. Bursting could be recovered by decreasing the time constant of I_{DR} activation, which would make the steady state less repelling. Also, increasing the efficiency of I_A by slowing its inactivation variable or increasing its conductance would help bring the

trajectory toward the unstable steady state. However, note that increasing g_A could create a stable hyperpolarized steady state (see Figure 7B) of the full V - n - e system, so the steepness of the activation function of I_A would need to be increased. Thus, bursting is robust to parameter changes, but others may not have observed this type of I_A -induced bursting because of the location of the unstable steady state or the time-dependent properties of the I_A and I_{DR} currents used in their models. To our knowledge, this is the first example of bursting without a slow variable in a single-compartment, physiologically based cell model.

Acknowledgments

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