

**Set 21: Systems of First Order Linear  
Equations Part 2**

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## Complex Eigenvalues

- If a real matrix  $A$  has a complex eigenvalue  $\lambda = \alpha + i\beta$  then  $\bar{\lambda} = \alpha - i\beta$  must also be an eigenvalue.
- This follows from the fact that  $\det(A - \lambda I)$  is a polynomial of degree  $n$  with real coefficients.
- We want real valued solutions to

$$x' = Ax$$

- The eigenvectors of  $A$  corresponding to  $\lambda$  and  $\bar{\lambda}$  will be complex.

## Eigenvectors of Conjugate Eigenvalues

**Lemma 21.1.** *If the matrix  $A \in \mathbb{R}^{n \times n}$  has conjugate eigenvalues  $\lambda_1 = \alpha + i\beta$  and  $\lambda_2 = \bar{\lambda} = \alpha - i\beta$  with eigenvectors  $z^{(1)}$  and  $z^{(2)}$  respectively then*

$$z^{(1)} = a + ib \quad \text{and} \quad z^{(2)} = a - ib = \overline{z^{(1)}}$$

*where  $a \in \mathbb{R}^n$  and  $b \in \mathbb{R}^n$*

## Eigenvectors of Conjugate Eigenvalues

*Proof.* This follows from direct computation. Since for any two complex scalars we know  $\overline{(\gamma\delta)} = \overline{\gamma} \overline{\delta}$  we have

$$Av^{(1)} = z^{(1)} \lambda_1$$

$$\overline{Az^{(1)}} = \overline{z^{(1)} \lambda_1}$$

$$\overline{A} \overline{z^{(1)}} = \overline{z^{(1)}} \overline{\lambda_1}$$

$$A\overline{z^{(1)}} = \overline{z^{(1)}} \overline{\lambda_1}$$

$$Az^{(2)} = z^{(2)} \lambda_2$$

□

## Solutions

$$\begin{aligned}x^{(1)}(t) &= z^{(1)}e^{(\alpha+i\beta)t} = (a+ib)e^{(\alpha+i\beta)t} \\ &= e^{\alpha t}(a \cos \beta t - b \sin \beta t) + ie^{\alpha t}(a \sin \beta t + b \cos \beta t) = u(t) + iv(t)\end{aligned}$$

It can be shown that  $u(t)$  and  $v(t)$  are linearly independent solutions to the ODE.

## Solutions

If the matrix  $A \in \mathbb{R}^{n \times n}$  has conjugate eigenvalues  $\lambda_1 = \alpha + i\beta$  and  $\lambda_2 = \bar{\lambda} = \alpha - i\beta$  with eigenvectors  $z^{(1)} = a + ib$  and  $z^{(2)} = a - ib$  and distinct eigenvalues  $\lambda_3, \dots, \lambda_n$  with real eigenvectors  $v^{(3)}, \dots, v^{(n)}$  then a general solution of  $x' = Ax$  is

$$c_1 u(t) + c_2 v(t) + c_3 v^{(3)} e^{\lambda_3 t} + \dots + c_n v^{(n)} e^{\lambda_n t}$$

$$u(t) = e^{\alpha t} (a \cos \beta t - b \sin \beta t)$$

$$v(t) = e^{\alpha t} (a \sin \beta t + b \cos \beta t)$$

The result is straightforward to adapt to multiple conjugate pairs and distinct real eigenvalues.

## Example

Textbook p. 401

$$x' = Ax$$

$$A = \begin{pmatrix} -0.5 & 1 \\ -1 & -0.5 \end{pmatrix}$$

$$\det(A - \lambda I) = \begin{vmatrix} -0.5 - \lambda & 1 \\ -1 & -0.5 - \lambda \end{vmatrix} = \lambda^2 + \lambda + \frac{5}{4}$$

$$\lambda_{\pm} = -0.5 \pm 0.5i\sqrt{4} = -0.5 \pm i$$

## Example

$$(A - \lambda_1 I)z^{(1)} = 0$$

$$\begin{pmatrix} -0.5 - (-0.5 + i) & 1 \\ -1 & -0.5 - (-0.5 + i) \end{pmatrix} \begin{pmatrix} z_1 \\ z_2 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$$

$$\begin{pmatrix} -i & 1 \\ -1 & -i \end{pmatrix} \begin{pmatrix} z_1 \\ z_2 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$$

$$\therefore z_2 = iz_1$$

$$z^{(1)} = \begin{pmatrix} 1 \\ i \end{pmatrix} \rightarrow x^{(1)}(t) = \begin{pmatrix} 1 \\ i \end{pmatrix} e^{(-0.5+i)t}$$

## Example

$$x^{(1)}(t) = \begin{pmatrix} 1 \\ i \end{pmatrix} e^{(-0.5+i)t} = \begin{pmatrix} 1 \\ i \end{pmatrix} e^{-0.5t} (\cos t + i \sin t)$$

$$x^{(1)}(t) = \begin{pmatrix} e^{-0.5t} \cos t \\ -e^{-0.5t} \sin t \end{pmatrix} + i \begin{pmatrix} e^{-0.5t} \sin t \\ e^{-0.5t} \cos t \end{pmatrix}$$

$$u(t) = \begin{pmatrix} e^{-0.5t} \cos t \\ -e^{-0.5t} \sin t \end{pmatrix} \quad v(t) = \begin{pmatrix} e^{-0.5t} \sin t \\ e^{-0.5t} \cos t \end{pmatrix}$$

## Example

$$\begin{aligned} W[u, v](t) &= \begin{vmatrix} e^{-0.5t} \cos t & e^{-0.5t} \sin t \\ -e^{-0.5t} \sin t & e^{-0.5t} \cos t \end{vmatrix} \\ &= e^{-t} (\cos^2 t + \sin^2 t) \neq 0 \end{aligned}$$

$$x(t) = c_1 \begin{pmatrix} e^{-0.5t} \cos t \\ -e^{-0.5t} \sin t \end{pmatrix} + c_2 \begin{pmatrix} e^{-0.5t} \sin t \\ e^{-0.5t} \cos t \end{pmatrix}$$