

## Set 5: First Order ODEs - Part 4

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Ordinary Differential Equations  
Fall 2009

1

### Linear First Order ODEs

**Corollary 5.2.** *The unique solution  $y = \phi(t)$  on  $I$  to the initial value problem under the conditions of Theorem 5.1 is given by*

$$y(t) = \frac{1}{\mu(t)} \left[ y_0 + \int_{t_0}^t \mu(s)g(s)ds \right]$$
$$\mu(t) = e^{z(t)}$$
$$z(t) = \int_{t_0}^t p(t)dt$$

(Note that  $\mu(t_0) = 1$ .)

3

### Linear First Order ODEs

**Theorem 5.1** (Textbook page 68). *If  $p(t)$  and  $g(t)$  are continuous on an open interval  $I : \alpha < t < \beta$  then there exists a unique solution  $y = \phi(t)$  on  $I$  to the initial value problem*

$$y' + p(t)y = g(t)$$
$$y(t_0) = y_0, \quad \alpha < t_0 < \beta$$

for any value of  $y_0$ .

2

### Linear First Order ODEs

**Corollary 5.3.** *All possible solutions to the differential equation on  $I$  under the conditions of Theorem 5.1 are given by the general solution*

$$y(t) = \frac{1}{\mu(t)} \left[ C + \int_{t_0}^t \mu(s)g(s)ds \right]$$
$$\mu(t) = e^{z(t)}$$
$$z(t) = \int_{t_0}^t p(t)dt$$

4

### Linear First Order ODEs

Assuming the conditions of Theorem 5.1:

- A general solution in explicit form is known that characterizes all solutions to the ODE.
- A particular solution to an IVP results by setting  $C = y_0$
- The solution requires only two antiderivatives.
- Possible points of discontinuity or singularity of the solution  $y(t)$  can be identified from  $p(t)$  and  $g(t)$ .
- The conditions given are sufficient not necessary. It is possible for the solution  $y(t)$  to be continuous even when  $p(t)$  and/or  $g(t)$  are/is discontinuous.

5

### Some Solutions of Interest

Applying Theorem 5.1 to  $y' + (2/t)y = 4t$  yields:

$$\begin{aligned}y(1) = 2 &\rightarrow y(t) = t^2 + \frac{1}{t^2}, & 0 < t < \infty, & \text{discontinuous} \\y(-1) = 2 &\rightarrow y(t) = t^2 + \frac{1}{t^2}, & -\infty < t < 0, & \text{discontinuous} \\y(1) = -1 &\rightarrow y(t) = t^2 - \frac{2}{t^2}, & 0 < t < \infty, & \text{discontinuous} \\y(-1) = -1 &\rightarrow y(t) = t^2 - \frac{2}{t^2}, & -\infty < t < 0, & \text{discontinuous} \\&\therefore \text{discontinuous } y(t) \rightarrow \text{discontinuous } p(t)\end{aligned}$$

7

### Example

Recall, the linear first order ODE:

$$ty' + 2y = 4t^2 \rightarrow y' + \frac{2}{t}y = 4t$$

$$p(t) = \frac{2}{t} \quad \text{and} \quad g(t) = 4t$$

$$\text{General solution: } y(t) = t^2 + \frac{C}{t^2}$$

Possible problem points?

- $g(t)$  is continuous for  $-\infty < t < \infty$ ,  $\therefore$  no problem
- $p(t)$  is continuous for  $t < 0$  and  $t > 0$ ,  $\therefore$  possible problem at  $t = 0$

6

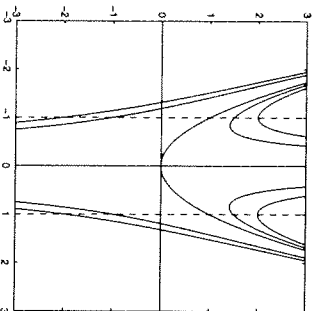
### Some Solutions of Interest

Applying Theorem 5.1 to  $y' + (2/t)y = 4t$  yields:

$$\begin{aligned}y(0) = 0 &\rightarrow y(t) = t^2, & \infty < t < \infty \\&\text{continuous on entire real line} \\&\therefore \text{discontinuous } p(t) \nrightarrow \text{discontinuous } y(t) \\&\therefore \text{discontinuous points of } p(t) \text{ and } g(t) \text{ only possibly a problem.}\end{aligned}$$

8

### Example: Integral Curves



Nine solutions for  $y' + \frac{2}{3}y = 4t$  with multiple initial conditions at  $x = \pm 1, 0$ .

9

### Nonlinear First Order ODEs

- $\partial f / \partial y$  is used because we want  $t$  to be the independent variable.
- The conditions are sufficient not necessary.
- The solution is guaranteed to exist on a subinterval not on the entire  $t$  interval defining  $\mathcal{R}$ . The subinterval is, in general, not easy to determine from the differential equation only.
- If  $f$  or  $\partial f / \partial y$  are discontinuous somewhere in  $\mathcal{R}$  the theorem says nothing about the situation. There may be none, one or more solutions on all or part of  $\mathcal{R}$ .

11

### Nonlinear First Order ODEs

**Theorem 5.4** (Textbook page 70). *If  $f(t, y)$  and its partial derivative  $\partial f / \partial y$  are continuous in the rectangle*

$$\mathcal{R} = \{(t, y) : \alpha < t < \beta, \gamma < y < \delta\}$$

*then there is a unique solution  $y = \phi(t)$  of the initial value problem*

$$y' = f(t, y), \quad y(t_0) = y_0, \quad (t_0, y_0) \in \mathcal{R}$$

*defined on some subinterval around  $t_0$*

$$t_0 - h < t < t_0 + h$$

10

### Nonlinear First Order ODEs

- There is no general solution form for an arbitrary nonlinear first order ODE or an associated IVP.
- Identifying the form of all possible solutions or the solution with  $y(t_0) = y_0$  depends strongly on the class of nonlinear first order ODEs.
- We have seen one such class. For separable first order equations we have

$$M(x)dx + N(y)dy = 0$$

$$\int M(x)dx + \int N(y)dy = H_1(x) + H_2(y) = C$$

$$\int_{x_0}^x M(x)dx + \int_{y_0}^y N(y)dy = 0$$

12

**Example**

$$y' = \frac{(3x^2 + 4x + 2)}{(2y - 2)}$$

$y = 1 \rightarrow y' = \infty$  line of interest

$$f(x, y) = (3x^2 + 4x + 2)/(2y - 2)$$

$$\frac{\partial f}{\partial y}(x, y) = -\frac{(3x^2 + 4x + 2)}{2(y - 1)^2}$$

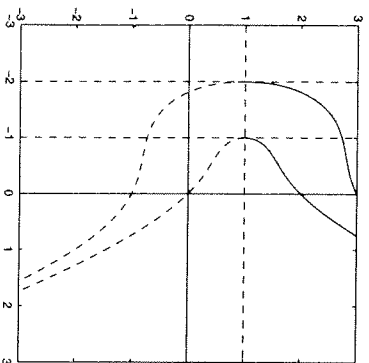
$$y(x) = 1 \pm \sqrt{c + 1 + x^3 + 2x^2 + 2x}$$

13

**Example**

- Theorem 5.4 guarantees unique solution on some interval in  $x$  within any rectangle  $\mathcal{R}$  that does not contain any part of the line  $y = 1$ .
- Consider initial conditions  $(0, 3)$ ,  $(0, 2)$ ,  $(0, 0)$ , and  $(0, -1)$ . All unique but not defined on entire  $x$  axis.
- Subinterval determined by where solution for a particular initial condition crosses  $y = 1$ .
- In this case the solutions become complex, i.e., they do not blow up in magnitude.
- Consider  $(-2, 1)$  and  $(-1, 1)$ . Theorem 5.4 says nothing but two solutions each!

14

**Example**

$$y' = (3x^2 + 4x + 2)/(2y - 2), (x_0, y_0) = (0, 3), (0, 2), (0, 0), (0, -1).$$

15

**Example**

Some times the singularities, i.e., points where solutions go to  $\infty$  in magnitude, are not expected from the ODE form.

$$y' = y^2, \quad y(0) = y_0$$

$$f(t, y) = y^2$$

$$\frac{\partial f}{\partial y}(t, y) = 2y$$

Continuous everywhere in  $(t, y)$  plane therefore a unique solution exists for any initial condition

16

### Example

$$y(t_0) = y_0 \rightarrow y(t) = \frac{y_0}{1 - y_0 t}$$

$$\lim_{t \rightarrow \frac{1}{y_0}} |y(t)| = \infty$$

if  $y_0 > 0$  then  $|y(t)| < \infty$ ,  $-\infty < t < \frac{1}{y_0}$

if  $y_0 < 0$  then  $|y(t)| < \infty$ ,  $\frac{1}{y_0} < t < \infty$

- There is a singularity at a value of  $t$  that depends on the initial condition  $y_0$ .
- The ODE gives no indication that there is a problem!

17

### Discontinuous Coefficients

Consider the linear first order ODE

$$y' + p(t)y = g(t), \quad y(t_0) = y_0$$

Suppose there is a jump discontinuity in  $p(t)$  and/or  $g(t)$  at some point  $t_d$ .

The problem can be solved by solving the problems:

$$y_1' + p(t)y_1 = g(t), \quad y_1(t_0) = y_0, \quad t_0 \leq t \leq t_d$$

$$y_2' + p(t)y_2 = g(t), \quad y_2(t_d) = y_1(t_d), \quad t_d < t$$

This is done by exploiting the fact that we have two constants at our disposal from the two general solutions.

18

### Example

$$y' + 2y = g(t), \quad y(0) = 0$$

$$g(t) = \begin{cases} 1 & \text{if } 0 \leq t \leq 1 \\ 0 & \text{if } t > 1 \end{cases}$$

$$y_1' + 2y_1 = g(t), \quad y_1(0) = 0, \quad 0 \leq t \leq 1$$

$$\mu(t) = e^{2t}$$

$$y_1(t) = C_1 e^{-2t} + e^{-2t} \int e^{2t} dt = C_1 e^{-2t} + \frac{1}{2}$$

$$y_1(0) = 0 \rightarrow C_1 = -\frac{1}{2}, \quad y_1(t) = \frac{1}{2}(1 - e^{-2t})$$

19

### Example

$$y_2' + 2y_2 = g(t) = 0, \quad t > 1, \quad y_2(1) = y_1(1)$$

$$y_2(t) = C_2 e^{-2t}$$

$$y_2(1) = C_2 e^{-2} = y_1(1) = \frac{1}{2}(1 - e^{-2})$$

$$\therefore C_2 = \frac{1}{2}(e^2 - 1) \quad \text{and} \quad y_2(t) = \frac{1}{2}(e^2 - 1)e^{-2t}$$

$$y(t) = \begin{cases} \frac{1}{2}(1 - e^{-2t}) & \text{if } 0 \leq t \leq 1 \\ \frac{1}{2}(e^2 - 1)e^{-2t} & \text{if } t > 1 \end{cases}$$

20