# Frame theory on vector bundles

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Frames (through a geometric lens)

Vector Bundles

Frames Fields on Vector Bundles

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(Frame inequality)

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Henceforth *V* is finite dimensional and  $C = \{v_1, \dots v_k\}$ 

A subset  $C = \{v_1, \dots v_k\}$  of V gives rise to an *Analysis operator*  $A_C : V \to \mathbb{R}^k$ 

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$$\sum_{i} \langle v, v_i \rangle^2 = ||A_{\mathcal{C}}(v)||^2 \leqslant ||A_{\mathcal{C}}||_{op}^2 ||v||^2 < \infty$$

so upper frame inequality is automatic for finite subsets

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Frames (through a geometric lens)

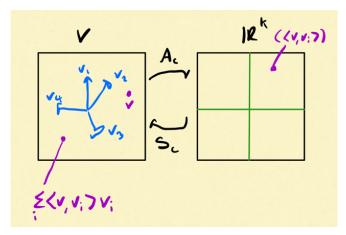
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Moral: Finite frames in  $V \Leftrightarrow$  Spanning sets of  $V \Leftrightarrow$  surjective  $M : \mathbb{R}^k \to V$ 

## Frame operator

### Given a frame C, we can define the frame operator

$$F_{\mathcal{C}} = S_{\mathcal{C}} \circ A_{\mathcal{F}} : V \to V$$



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The map  $F_{\mathcal{C}}^{-1}S_{\mathcal{C}}:\mathbb{R}^k\to V$  is the Moore-Penrose Pseudoinverse,  $A_{\mathcal{C}}^{\dagger}$ , of  $A_{\mathcal{C}}$ 

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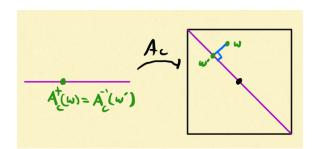
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### Moore Penrose Pseudoinverse

The Moore Penrose Pseudoinverse is easy to describe geometrically.

Given  $w \in \mathbb{R}^k$  we...

- Orthogonally project w to  $Im(A_C)$
- Take inverse of A<sub>C</sub>



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Frames of this type are called *Parseval frames* 

These generalize notion of orthonormal bases

Alternate characterizations

Parseval frames can be described in a variety of equivalent ways

- $F_C = S_C A_C = A_C^t A_C = I$
- a = b = 1 in frame inequality
- A<sub>C</sub>: V → ℝ<sup>k</sup> is an isometric embedding (preserves inner products)

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Question: How does size of v' - v compare to  $w' - w = \eta$ ?

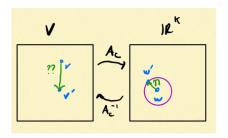
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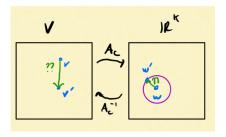
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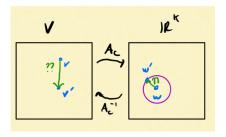


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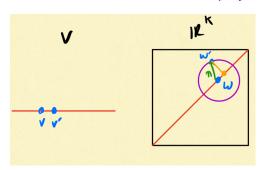


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If the basis is orthonormal  $A_{\mathcal{C}}$  is maximally well conditioned

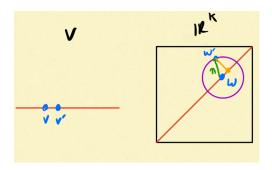
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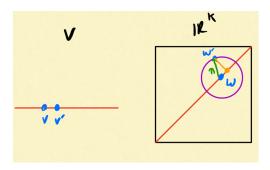
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If the frame is Parseval the  $A_C$  is again maximally well conditioned



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Moral: The larger the frame, the more robust it is to noise!

Frames (through a geometric lens

**Vector Bundles** 

Frames Fields on Vector Bundles

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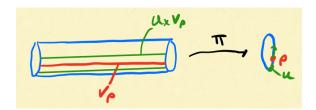
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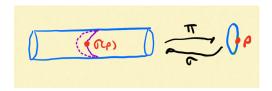
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- $\pi^{-1}(p) = V_p$  (fiber)
- There is a nbhd  $p \in U$  of each p so that  $\pi^{-1}(U) \cong U \times V_p$  (locally a product)



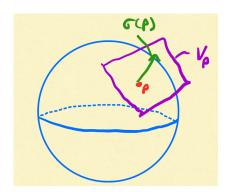
#### Vector fields

A *vector field* is a (continuous) choice of a vector in each fiber More precisely, a vector field is a continuous  $\sigma: M \to E$  so that  $\pi \circ \sigma = Id$   $(\sigma(p) \text{ lives in } V_p)$ 



## A toy example

- $M = S^2$  (surface of earth)
- $V_p$  =tangent vectors at p
- *E* =tangent bundle to *S*<sup>2</sup>
- $\sigma = \text{wind velocity}$



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Question: given measuring devices  $\mu_1, \ldots, \mu_k$  can we recover a vector field  $\sigma : M \to E$  from  $\mu_1(\sigma), \ldots, \mu_k(\sigma)$ ?

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Question: given measuring devices  $\mu_1, \ldots, \mu_k$  can we recover a vector field  $\sigma: M \to E$  from  $\mu_1(\sigma), \ldots, \mu_k(\sigma)$ ? Yes iff  $\{\mu_1(p), \ldots, \mu_k(p)\}$  is a frame in  $V_p$  for each p. Frames (through a geometric lens

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Let  $E \to M$  be a vector bundle. A collection  $\{\mu_1, \dots, \mu_k\}$  of vector fields is a *frame field of size* k if  $\{\mu_1(p), \dots, \mu_k(p)\}$  is a frame for each  $p \in M$ .

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- Can we always find a Parseval frame field?

revisited

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Global bases don't usually exist!

revisited

What about a frame field of size 3?

# Toy Example

revisited

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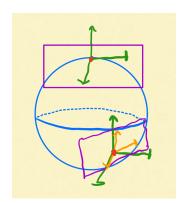
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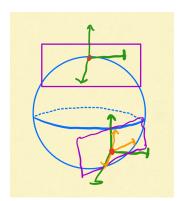


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revisited

What about a frame field of size 3? Yes! It's even Parseval!

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This generalizes previous work by Freeman-Poore-Wei-Wyse

 Build a (non-vector) bundle P<sub>k</sub>(V) → M whose fiber at p is the "space of all Parseval frames" of size k in V<sub>p</sub>

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- By fixing an orthonormal basis on V<sub>p</sub>, the space of all Parseval frames of size k can be identified with orthonormal subsets of R<sup>k</sup> of size n (Stiefel manifold S<sub>n</sub>(R<sup>k</sup>)) using analysis operator

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- If k ≥ d + n then all the obstructions vanish and we can find a section.

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- Analyze robustness properties of Parseval frames for various types of noise
- Study minimal frame dimension

   (i.e. Given E → M find smallest n ≤ k ≤ n + d so that a k-frame field exists

## Have Hammer, Seeking Nail

Please let me know if you have potential applications



# Thank you!