

Divergence in Coxeter groups

Ignat Soroko

University of North Texas

ignat.soroko@unt.edu

Joint work with

Pallavi Dani, Louisiana State University

Yusra Naqvi, University College London

Anne Thomas, University of Sydney

BG–UToledo joint Geometry and Topology seminar
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Geometry of groups

Let G be a finitely presented group: $G = \langle A \mid R \rangle$

$$1 \longrightarrow \langle\langle R \rangle\rangle \longrightarrow F(A) \longrightarrow G \longrightarrow 1$$

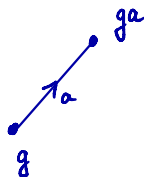
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Geometric models:

- Cayley graph: $\text{Cay}_A^1(G)$:
 - $\{\text{vertices}\} \longleftrightarrow G$
 - $\{\text{directed edges}\} \longleftrightarrow G \times A$



- Cayley 2-complex: $\text{Cay}_{\langle A \mid R \rangle}^2(G)$
 - attach 2-cells to the Cayley graph $\text{Cay}_A^1(G)$ equivariantly

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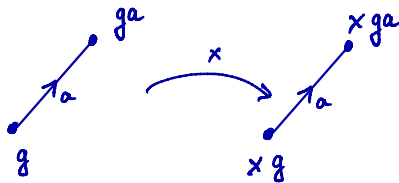
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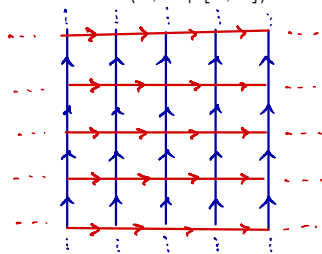
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G acts on $\text{Cay}_A^1(G)$ and $\text{Cay}_{\langle A \mid R \rangle}^2(G)$ by isometries.

Examples:

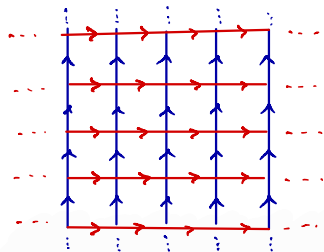
$$\mathbb{Z} \times \mathbb{Z} = \langle a, b \mid [a, b] \rangle:$$



$$\text{Cay}_{\langle A, B \rangle}^{\mathbb{Z}} = \mathbb{R}^2$$

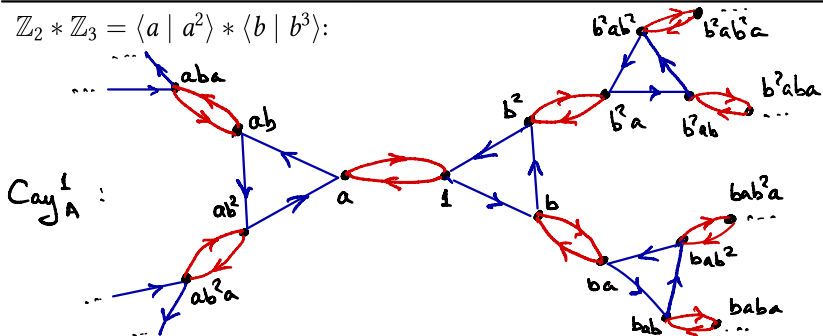
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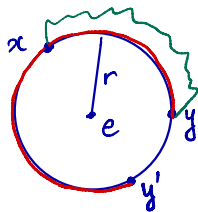
$$\mathbb{Z}_2 * \mathbb{Z}_3 = \langle a \mid a^2 \rangle * \langle b \mid b^3 \rangle:$$



Divergence

Let

- X be a 1-ended geodesic metric space
- e basepoint,
- $S(e, r)$ sphere of radius r around e



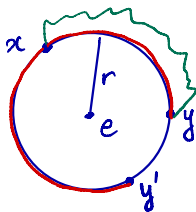
The **divergence** of X is:

$$\operatorname{div}_X(r) = \sup_{x, y \in S(e, r)} \inf(\text{lengths of } r\text{-avoidant paths from } x \text{ to } y)$$

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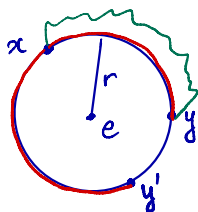
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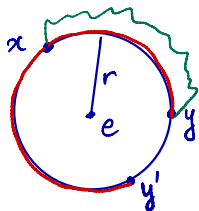
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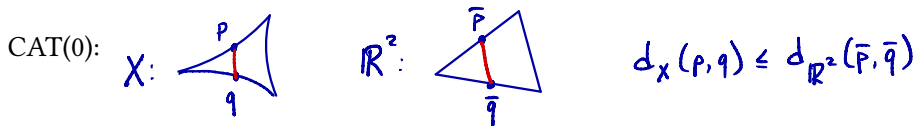
- ▶ \mathbb{R}^2 : $\operatorname{div}_{\mathbb{R}^2}(r) = \pi r$, linear
- ▶ \mathbb{H}^2 : $\operatorname{div}_{\mathbb{H}^2}(r) = \pi \sinh(r) \sim \pi e^r / 2$, exponential

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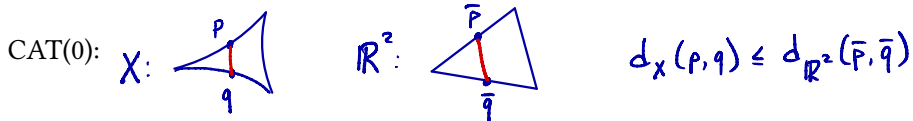
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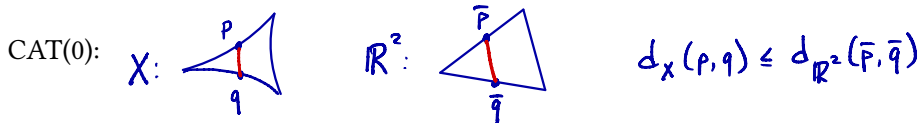
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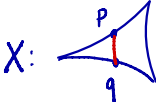
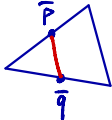
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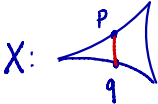
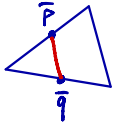
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- Brady-Tran (2021): $\text{div}_G \sim r^\alpha$ for α dense in $[2, \infty)$
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$\left. \begin{array}{l} F_n \times \mathbb{Z} \\ \varphi \\ \varphi \in \text{Aut}(F_n) \end{array} \right\}$

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Q: Given your favorite class of groups, what spectrum of divergence functions does it have?

Coxeter groups

A Coxeter group W is given by:

- finite set S
- symmetric matrix $(m_{st})_{s,t \in S}$ such that:

$$m_{ss} = 1, m_{st} = m_{ts} \in \{2, 3, 4, \dots, \infty\}$$

(W, S) is given by presentation:

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Encoded by a **Coxeter graph** (a.k.a. Dynkin graph) with edges labeled m_{st} :

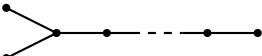


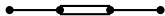
Spherical Coxeter groups = finite

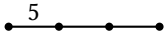
Here's the list of irreducible ones (Coxeter, 1935):

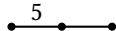
$A_n, (n \geq 1)$: 

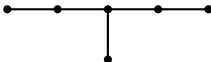
$B_n, (n \geq 2)$: 

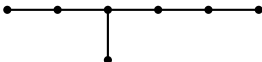
$D_n, (n \geq 4)$: 

F_4 : 


H_4 : 

H_3 : 

E_6 : 


E_7 : 

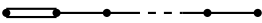
E_8 : 

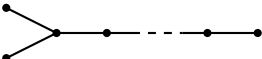
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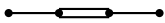
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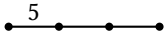
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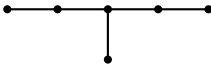
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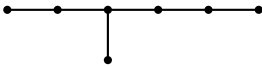
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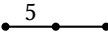

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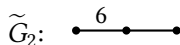
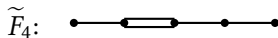
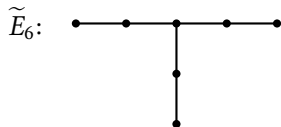
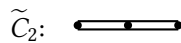
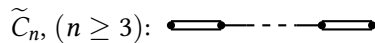
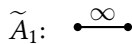
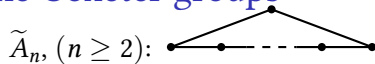
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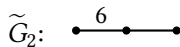
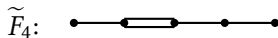
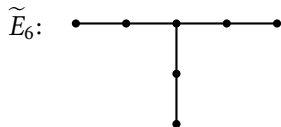
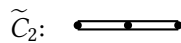
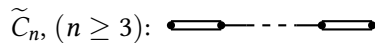
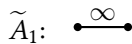
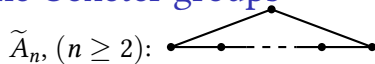
H_3 :  $(m \geq 5, m \neq \infty)$: 

Groups generated by reflections in
the faces of a simplex in S^n

Affine Coxeter groups




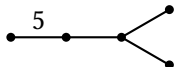
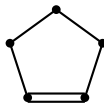
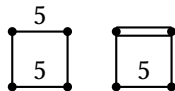
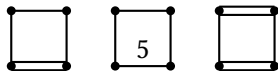
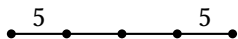
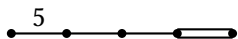
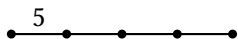
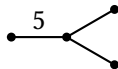
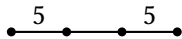
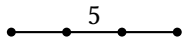
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
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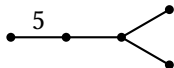
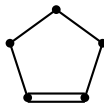
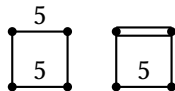
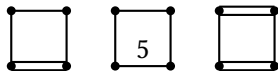
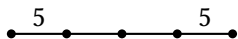
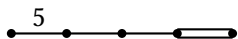
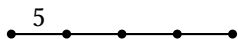
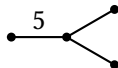
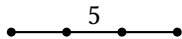
Lannér's hyperbolic Coxeter groups


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Groups generated by reflections in the faces of a simplex in \mathbb{H}^n

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Theorem 1

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Let (W, S) be a 1-ended Coxeter system. Then W has linear divergence if and only if $(W, S) = (W_1, S_1) \times (W_2, S_2)$ where either

- both W_1 and W_2 are infinite, or*
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Corollary 3

If a 1-ended Coxeter group has a super-linear divergence, then its divergence is at least quadratic.

I.e. there is a gap between r and r^2 .

*similar is true for
Dehn functions*

Our results, part II

$$m_{st} = 2, \infty$$

Ivan Levcovitz introduced what he called a **hypergraph index** for RACGs, which is an integer ≥ 0 or ∞ , computable directly from the Coxeter graph.

We generalize it for general Coxeter groups.

Theorem 4

1. $h = 0 \iff W$ has linear divergence.
2. $h = 1 \implies W$ has quadratic divergence.
3. h is finite \implies the divergence of W is bounded above by a polynomial of degree $h + 1$.
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We proved it for certain series of non-right-angled Coxeter groups.

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Let (W, S) be a Coxeter system with the Coxeter graph $\Delta = \Delta(W, S)$ and hypergraph index $h = h(W, S)$. If h is finite then $h \leq b_1(\Delta) + 1$, where $b_1(\Delta)$ is the 1-st Betti number of Δ .

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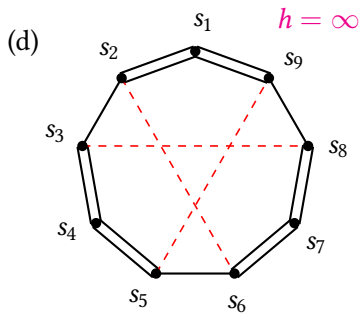
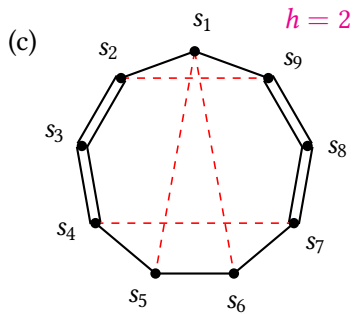
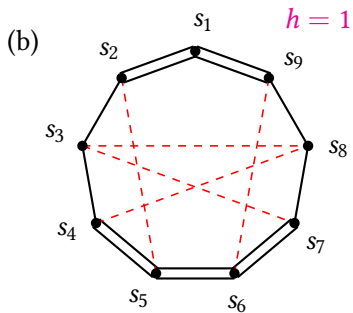
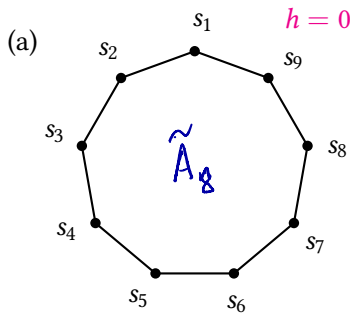
$$b_1(\Delta) = e - v + k, \quad v = \#\text{vertices}, \quad e = \#\text{edges}, \quad k = \#\text{components}.$$

Corollary 6

If a Coxeter group W is not relatively hyperbolic, then the divergence of W is *bounded above* by a polynomial of degree $b_1(\Delta) + 2$.

Corollary 7

If the Coxeter graph of (W, S) is a tree and W is 1-ended, then W has divergence *linear, quadratic or exponential* only. Moreover, each of these possibilities is realized.



Key idea

Behrstock–Caprace–Hagen–Sisto (2017): A Coxeter group W is either:

- relatively hyperbolic $\implies \text{div} \simeq \text{exponential}$
- thick $\implies \text{div is } \preceq \text{ a polynomial}$

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A **relatively hyperbolic** group H has a family of **peripheral subgroups** P_i :

- (1) Each $\mathbb{Z} \times \mathbb{Z}$ subgroup of H must be contained in some of P_i
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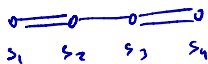
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Plan: Build candidates for peripheral subgroups $P_i \subseteq W$ forced by (1) and (2). Start with obvious subgroups containing $\mathbb{Z} \times \mathbb{Z}$ and take their joins if they intersect infinitely. Once the process stops:

- ▶ if no subgroup P_i equal W : we get an honest peripheral structure and W is relatively hyperbolic $\implies \text{div} \simeq \text{exponential}$
- ▶ if some $P_i = W$, the Coxeter group W is thick, and the number of steps before stabilization is our **hypergraph index** $h \implies \text{div} \preceq r^{h+1}$.

More formally:

S : set of gens



Wide subsets: $\Omega(S) =$ maximal sets of the form $A \times B$ where

- A, B both nonspherical, or
- A irreducible affine of $\text{rk} \geq 3$, B spherical (or empty)

obviously
contain $\mathbb{Z} \times \mathbb{Z}$

Slab subsets: $\Psi(S) =$ maximal sets of the form: $A \times K$, such that

- A is minimal nonspherical
- K is maximal nonempty spherical, commuting with A
- there does not exist $T \in \Omega(S)$ such that $A \times K \subseteq T$.

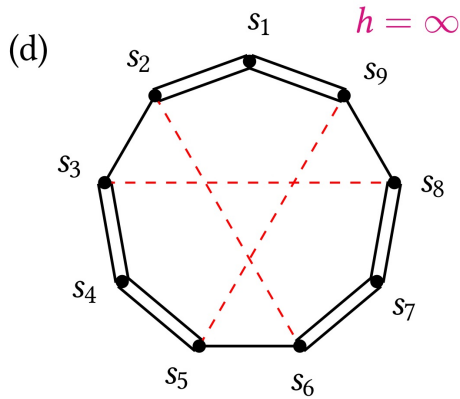
a tool to
detect when
two peripheral
intersect in an
infinite subgroup

Define: $\Lambda_0(S) = \Omega(S) \cup \Psi(S)$,

$\Lambda_{i+1}(S) =$ set of all unions of elements in \equiv_i equivalence class on $\Lambda_i(S)$, generated by the condition " $T \cap T'$ is nonspherical"

Then the **hypergraph index** h is:

- if $S \in \Lambda_h(S) \setminus \Lambda_{h-1}(S)$ and $\Omega(S) \neq \emptyset$: $h \in \mathbb{N}$
- otherwise $h = \infty$



$$T_1: \begin{array}{c} s_1 \quad s_9 \quad s_8 \quad s_7 \\ \text{---} \text{---} \text{---} \text{---} \\ \tilde{C}_3 \end{array} \times \begin{array}{c} s_3 \quad s_4 \quad s_5 \\ \text{---} \text{---} \text{---} \\ \tilde{C}_2 \end{array}$$

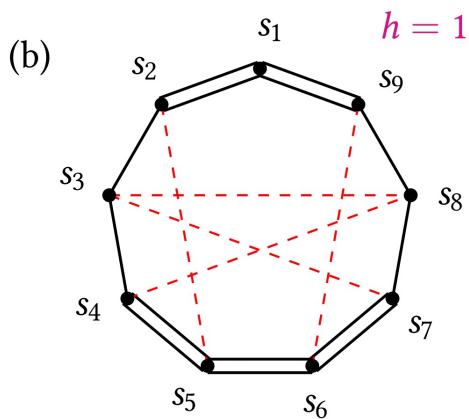
$$T_2: \begin{array}{c} s_1 \quad s_2 \quad s_3 \quad s_4 \\ \text{---} \text{---} \text{---} \text{---} \\ \tilde{C}_3 \end{array} \times \begin{array}{c} s_6 \quad s_7 \quad s_8 \\ \text{---} \text{---} \text{---} \\ \tilde{C}_2 \end{array}$$

$$T_3: \begin{array}{c} s_4 \quad s_5 \quad s_6 \quad s_7 \\ \text{---} \text{---} \text{---} \text{---} \\ \tilde{C}_3 \end{array} \times \begin{array}{c} s_2 \quad s_1 \quad s_9 \\ \text{---} \text{---} \text{---} \\ \tilde{C}_2 \end{array}$$

$$\Lambda_0 = \langle T_1, T_2, T_3 \rangle$$

$$T_i \cap T_j = \begin{array}{c} \text{---} \text{---} \times \text{---} \text{---} \times \circ \\ C_2 \times C_2 \quad A_1 \end{array}, \text{ spherical i.e. finite!}$$

$\Lambda_1 = \Lambda_0$, relatively hyperbolic with peripheral subgroups $\{W_{T_1}, W_{T_2}, W_{T_3}\}$ $h = \infty$

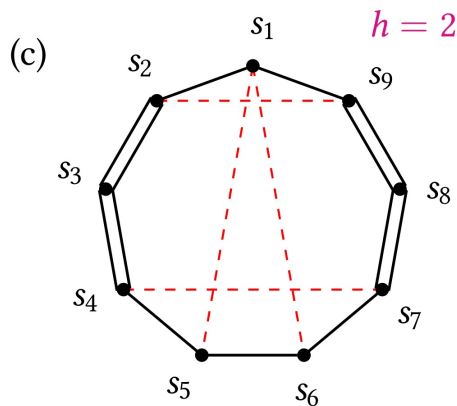


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$$T_1 \cup T_2 = \text{all of } S \quad h=1$$



$$T_1 = S \setminus \{s_1, s_5\} = \begin{array}{c} s_2 \quad s_3 \quad s_4 \\ \text{---} \text{---} \end{array} \times \begin{array}{c} s_6 \quad s_7 \quad s_8 \quad s_9 \\ \text{---} \text{---} \text{---} \end{array}$$

$$T_2 = S \setminus \{s_1, s_6\} = \begin{array}{c} s_2 \quad s_3 \quad s_4 \quad s_5 \\ \text{---} \text{---} \text{---} \end{array} \times \begin{array}{c} s_7 \quad s_8 \quad s_9 \\ \text{---} \end{array}$$

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$$T_4 = T_1 \cup T_2 = S \setminus \{s_1\}$$

$$T_3 = S \setminus \{s_2, s_9\} = \begin{array}{c} s_3 \quad s_4 \quad s_5 \quad s_6 \quad s_7 \quad s_8 \\ \text{---} \text{---} \text{---} \text{---} \end{array} \times \begin{array}{c} s_1 \\ \text{---} \end{array} = \tilde{C}_5 \times A_1$$

$$T_3 \cap T_4 = \tilde{C}_5, \text{ nonspherical}, \quad T_5 = T_3 \cup T_4 = S. \quad h=2$$