

Volumes spanned by k -point configurations in \mathbb{R}^d

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(joint work with Belmiro Galo)

Point Distribution Webinar
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The Falconer distance problem

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- The Falconer distance problem asks, for compact $E \subset \mathbb{R}^d$, how large the Hausdorff dimension of E must be to ensure that $\Delta(E)$ has positive (1-dimensional) Lebesgue measure.
- Falconer (1986) proved that the threshold $\dim E > \frac{d+1}{2}$ was sufficient, and that no threshold below $\frac{d}{2}$ is sufficient. The conjectured best threshold is $\frac{d}{2}$.

Results on the Falconer problem

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- The best current results are

$$\begin{cases} 5/4, & d = 2 \text{ (Guth, Iosevich, Ou, Wang)} \\ 9/5, & d = 3 \text{ (Du, Guth, Iosevich, Ou, Wang, Zhang)} \\ \frac{d}{2} + \frac{1}{4}, & d \geq 4, d \text{ even (Du, Iosevich, Ou, Wang, Zhang)} \\ \frac{d}{2} + \frac{1}{4} + \frac{1}{4(d-1)}, & d \geq 4, d \text{ odd (Du, Zhang)} \end{cases}$$

Strategy for Falconer problem

- If E is compact, for any $s < \dim E$ there is a probability measure μ supported on E such that

$$\mu(B_r(x)) \lesssim r^s$$

and

$$I_s(\mu) := \int \int |x - y|^{-s} d\mu(x) d\mu(y) < \infty.$$

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- The measure μ is called a Frostman probability measure with exponent s .

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- ν is a probability measure supported on $\Delta(E)$, so to prove $\Delta(E)$ has positive Lebesgue measure it suffices to show ν is absolutely continuous.

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- For $A \subset \mathbb{R}$, we have

$$\int_A \nu^\varepsilon(t) dt \lesssim |A|^{1/2} \|\nu^\varepsilon\|_{L^2}.$$

- The left hand side has limit $\nu(A)$, so it suffices to prove a bound on $\|\nu^\varepsilon\|_{L^2}$ which is independent of ε .

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- Given $\Phi : (\mathbb{R}^d)^N \rightarrow \mathbb{R}^M$, define ν by

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- If $\|\nu^\varepsilon\|_{L^2}$ is bounded independent of ε , then $\{\Phi(x^1, \dots, x^N) : x^i \in E\}$ has positive measure.

Congruence of point configurations

- A $(k + 1)$ -point configuration in \mathbb{R}^d is simply an element of $(\mathbb{R}^d)^{k+1}$, i.e., a $k + 1$ tuple $x = (x^1, \dots, x^{k+1})$ where each $x^i = (x_1^i, \dots, x_d^i)$ is a vector in \mathbb{R}^d .

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- We say $(k + 1)$ -point configurations x and y are congruent, and write $x \sim y$, if there exists $\theta \in O(\mathbb{R}^d)$, $z \in \mathbb{R}^d$ such that for all $i = 1, \dots, k + 1$ we have $y^i = \theta x^i + z$ (briefly, $y = \theta x + z$).

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- Given $E \subset \mathbb{R}^d$, let $\Delta_k(E)$ denote the set of congruence classes determined by E .
- We may identify $\Delta(E)$ with $\Delta_1(E)$.

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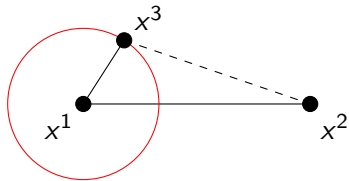
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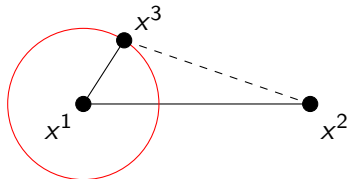
- Question: Given a compact set $E \subset \mathbb{R}^d$, how large must $\dim E$ be to ensure $\Delta_k(E)$ has positive measure?
- In order to pose this question, we must choose a measure on $\Delta_k(E)$.
- The choice of measure depends on whether $k \leq d$ or $k > d$.
- When $k \leq d$, each of the pairwise distances may be chosen independently. We may therefore identify $\Delta_k(E)$ with a subset of $\mathbb{R}^{\binom{k+1}{2}}$, equipped with $\binom{k+1}{2}$ -dimensional Lebesgue measure.

Example: The case $k = d = 2$



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- Let $x = (x^1, x^2, x^3)$ be a 3-point configuration in \mathbb{R}^2 .
- If we fix $|x^1 - x^2| = a$ and $|x^1 - x^3| = b$, the last distance $|x^2 - x^3|$ could take any value between $|a - b|$ and $a + b$.

Configuration congruence results in the $k \leq d$ case

Theorem (Greenleaf-Iosevich-Liu-Palsson, 2015)

Let $k \leq d$, and let $E \subset \mathbb{R}^d$ be a compact set. If

$$\dim E > d - \frac{d-1}{k+1},$$

then $\Delta_k(E)$ has positive $\binom{k+1}{2}$ -dimensional Lebesgue measure.

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■ In the case $k = 1$ this coincides with Falconer's $\frac{d+1}{2}$ threshold.

Overdetermined configurations

- When $k > d$, the system of equations

$$|x^i - x^j| = t_{i,j}$$

becomes overdetermined; by fixing some of the values $t_{i,j}$ we determine the others.

Overdetermined configurations

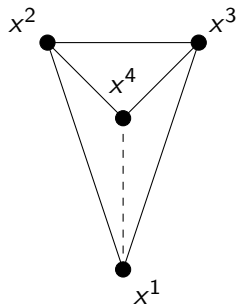
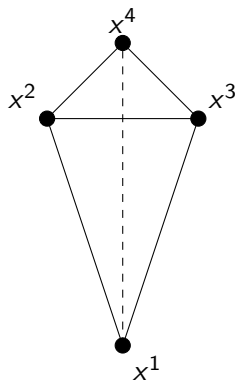
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- In this case we may still identify $\Delta_k(E)$ with $\binom{k+1}{2}$ -tuples of pairwise distances, but the resulting subset of $\mathbb{R}^{\binom{k+1}{2}}$ has measure zero.

Example: The case $k = 3, d = 2$



- With 4 points, if we fix 5 of the pairwise distances there are only 2 choices for the last distance.

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- Two non-degenerate configurations x, y are congruent if and only if there exists $\theta \in O(\mathbb{R}^d), z \in \mathbb{R}^d$ such that $y = \theta x + z$.
- The non-degenerate congruence classes can be identified with a space of dimension m , where

$$m = d(k+1) - \binom{d+1}{2}$$

Overdetermined congruence result

Theorem (Chatzikonstantinou-Iosevich-Mkrtchyan-Pakianathan, 2017)

Let $d \geq 2$ and $k \geq 1$, and let $m = d(k+1) - \binom{d+1}{2}$. Let $E \subset \mathbb{R}^d$ be compact. If $\dim E > d - \frac{1}{k+1}$, then $\Delta_k(E)$ has positive m -dimensional measure.

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- This approach generalizes to other overdetermined configuration problems if the relevant geometric features can be characterized in terms of a group action.

Volumes

Theorem (Greenleaf-Iosevich-Taylor, 2020)

Given $E \subset \mathbb{R}^d$, define

$$\mathcal{V}(E) = \{\det(x^1, \dots, x^d) : x^i \in E\}$$

If $E \subset \mathbb{R}^d$ is compact and $\dim E > d - 1 + \frac{1}{d}$, then $\mathcal{V}(E)$ has non-empty interior.

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- If $\dim E \leq d - 1$ then E may be contained in a hyperplane and determine no non-trivial volumes.
- It follows the threshold $d - 1 + \frac{1}{d}$ cannot be improved by more than $\frac{1}{d}$.

Volume types of point configurations

- Let x be a k -point configuration in \mathbb{R}^d , i.e.,

$$x = (x^1, \dots, x^k)$$

for vectors

$$x^j = (x_1^j, \dots, x_d^j) \in \mathbb{R}^d.$$

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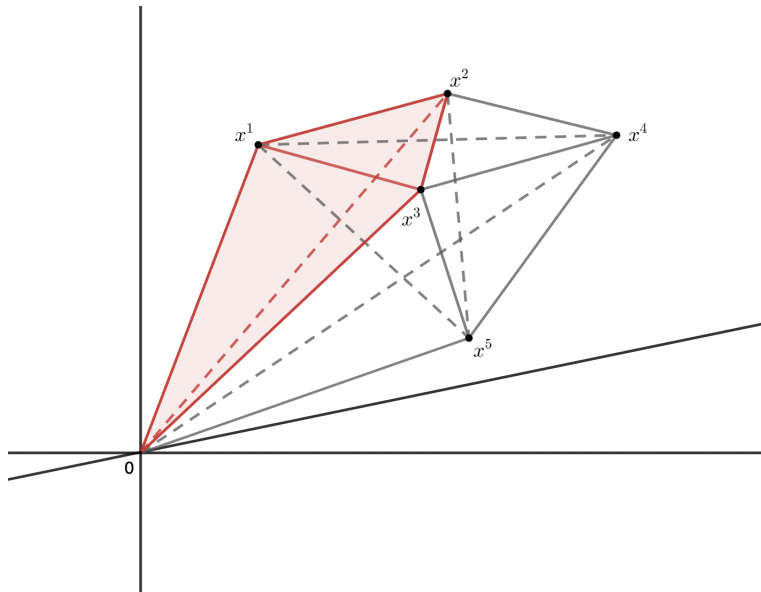
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- The **volume type** of x is the vector

$$\{\det(x^{i_1}, \dots, x^{i_d})\}_{1 \leq i_1 < \dots < i_d \leq k} \in \mathbb{R}^{\binom{k}{d}}.$$

A 5-point configuration in \mathbb{R}^3



Volume types of configurations

- Given $k \geq d$ and $E \subset \mathbb{R}^d$, let $\mathcal{V}_{k,d}(E)$ denote the set of volume types determined by configurations of points in E . Let $\mathcal{V}_{k,d} = \mathcal{V}_{k,d}(\mathbb{R}^d)$.

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- Let $\Phi_{k,d} : (\mathbb{R}^d)^k \rightarrow \mathcal{V}_{k,d}$ be the map taking configurations to their volume types.
- If $g \in \mathrm{SL}_d(\mathbb{R})$, it is clear that $\Phi_{k,d}(gx) = \Phi_{k,d}(x)$.

Volume types and the action of $SL_d(\mathbb{R})$

- Suppose $\Phi_{k,d}(x) = \Phi_{k,d}(y)$, and x^1, \dots, x^d are linearly independent.

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- Then $g \in SL_d(\mathbb{R})$, and $gx^i = y^i$ for $i = 1, 2, \dots, d$.

Volume types and group actions

- For $i > d$, write

$$x^i = \sum_{j=1}^d a_{i,j} x^j, \quad y^i = \sum_{j=1}^d b_{i,j} y^j.$$

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- Easy to prove $a_{i,j} = b_{i,j}$, so $gx^i = y^i$ for all i .
- For every non-degenerate x , there exists \tilde{x} of the form

$$\tilde{x} = (e^1, \dots, e^{d-1}, te^d, z^{d+1}, \dots, z^k)$$

with $\Phi_{k,d}(\tilde{x}) = \Phi_{k,d}(x)$.

Theorem

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- With this identification, our result is as follows.

Theorem (Galo-M., 2021)

Let $k \geq d \geq 2$, let $m = d(k - d) + 1$, and let $E \subset \mathbb{R}^d$ be compact. If $\dim E > d - \frac{d-1}{2k-d}$, then $\mathcal{L}_m(\mathcal{V}_{k,d}(E)) > 0$.

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- If $k = d$, then our threshold is $d - 1 + \frac{1}{d}$, which is the threshold in the Greenleaf-Iosevich-Taylor result.

Setup

- If E is compact, for any $s < \dim E$ there is a probability measure μ supported on E such that

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- Let $\nu_{k,t}^\varepsilon$ be the convolution of $\nu_{k,t}$ with an approximate identity. Our goal is to prove L^2 bounds on $\nu_{k,t}^\varepsilon$, independent of ε .

The $k = d$ case

- We have

$$\nu_{d,d}^\varepsilon(t) \approx \varepsilon^{-1} \int_{|\det(x^1, \dots, x^d) - t| < \varepsilon} d\mu^d(x)$$

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- Let ψ be a Schwartz function supported in the range $\frac{1}{2} \leq |\xi| \leq 4$ and constantly equal to 1 in the range $1 \leq |\xi| \leq 2$, and let $\hat{\mu}_j(\xi) = \psi(2^{-j}\xi)\hat{\mu}(\xi)$ be the corresponding Littlewood-Paley projection.

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- The above integral is

$$\varepsilon^{-1} \sum_{j_1 > \dots > j_d > 0} \int_{|\det(x^1, \dots, x^d) - t| < \varepsilon} \mu_{j_1}(x^1) \cdots \mu_{j_d}(x^d) dx$$

The $k = d$ case

- Define a generalized Radon transform by

$$\mathcal{R}_t f(x^1, \dots, x^{d-1}) = \int_{\substack{\det(x^1, \dots, x^d) = t \\ |x^1|, \dots, |x^d| \leq 1}} f(x^d) d\sigma_{t, x^1, \dots, x^{d-1}}(x^d),$$

where $\sigma_{t, x^1, \dots, x^{d-1}}$ is the surface measure.

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- The Greenleaf-Iosevich-Taylor result is obtained from this by studying the mapping properties of generalized Radon transforms.

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- This, together with Plancherel, gives bounds on the L^2 inner product

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$$\begin{aligned}\nu_{d,d}^\varepsilon(t) &\approx \sum_j \langle \mathcal{R}_t \mu_j, \mu_j \otimes \cdots \otimes \mu_j \rangle \\ &\approx \sum_j \|\mathcal{R}_t \mu_j\|_{L^2} \|\mu_j\|_{L^2}^{d-1}\end{aligned}$$

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$$\begin{aligned}\nu_{d,d}^\varepsilon(t) &\approx \sum_j \langle \mathcal{R}_t \mu_j, \mu_j \otimes \cdots \otimes \mu_j \rangle \\ &\approx \sum_j \|\mathcal{R}_t \mu_j\|_{L^2} \|\mu_j\|_{L^2}^{d-1} \\ &\approx \sum_j 2^{-\frac{d-1}{2}} \|\mu_j\|_{L^2}^d\end{aligned}$$

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The sum is finite when $s > d - 1 + \frac{1}{d}$.

Reducing to the $k = d$ case

- For general $k \geq d$, we have

$$\nu_{k,d}^\varepsilon(t) \approx \varepsilon^{-m} \int_{|\Phi_{k,d}(x)-t|<\varepsilon} d\mu^k(x).$$

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- Applying the bound $\|\mu_j\|_{L^\infty} \leq 2^{j(d-s)}$ to the last $k - d$ terms, this is

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Sharpness

Theorem (Galo-M.,2021)

Let $k \geq d \geq 2$. For any

$$s < d - \frac{d^2(d-1)}{d(k-1)+1},$$

there exists compact $E \subset \mathbb{R}^2$ such that $\dim E = s$ and $\mathcal{V}_{k,d}(E)$ has measure zero.

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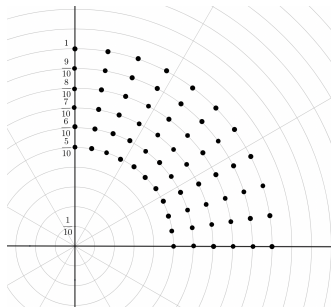
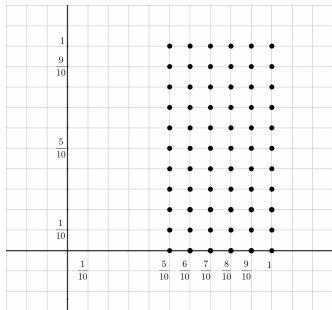
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- Take a lattice in the unit cube with spacing $1/q$ and thicken each point by $q^{-d/s}$.
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- Map the square lattice to a spherical lattice.

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- The thickened set has an volume type set of measure $\approx q^{d(k-1)+1} (q^{-d/s})^{d(k-d)+1}$.
- If $s < d - \frac{d^2(d-1)}{d(k-1)+1}$, this tends to zero as $q \rightarrow \infty$.

Distance chains

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- A natural Falconer-type question about point configurations asks how large the Hausdorff dimension of a set must be to ensure it determines a positive measure worth of distances corresponding to edges.
- The following result applies when G is a chain.

Theorem (Bennett-Iosevich-Taylor, 2015)

Let $d, k \geq 2$, and let $E \subset \mathbb{R}^d$ be compact. If $\dim E > \frac{d+1}{2}$, the set

$$\{(|x^1 - x^2|, \dots, |x^{k-1} - x^k|) : x^i \in E\}$$

has non-empty interior.

Distance trees

- This result was later generalized from chains to trees.

Theorem (Iosevich-Taylor, 2019)

Let $d, k \geq 2$ and let $E \subset \mathbb{R}^d$ be compact. Let T be a tree on the vertices $\{1, \dots, k\}$ with edge set \mathcal{E} . If $\dim E > \frac{d+1}{2}$, the set

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- For both chains and trees, the threshold does not depend on k .

Volume chains

- Our second result is an analogue for hypergraph chains of volumes.

Theorem (Galo-M., 2021)

Let $k, d \geq 2$ and let $E \subset \mathbb{R}^d$ be compact. If $\dim E > d - 1 + \frac{1}{d}$, then

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The $k = d + 1$ case

- Suppose $k = d + 1$. The quantity we want to bound is

$$\varepsilon^{-2} \int_{\substack{|\det(x^1, \dots, x^d) - t| < \varepsilon \\ |\det(x^2, \dots, x^{d+1}) - t'| < \varepsilon}} d\mu^{d+1}(x)$$

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- One can handle arbitrary $k \geq d$ by iterating this process.

The End

Thanks for listening!