## Rank-constrained Optimization: A Riemannian Manifold Approach

#### Guifang Zhou<sup>1</sup>, Wen Huang<sup>2</sup>, Kyle A. Gallivan<sup>1</sup>, Paul Van Dooren<sup>2</sup>, P.-A. Absil<sup>2</sup>

1- Florida State University 2- Université catholique de Louvain

23 April 2015

#### **Problem Statements**

• Finding an optimum of a rank-constrained problem

$$\min_{X\in\mathcal{M}_{\leq k}} f(X),$$

• 
$$\mathcal{M}_{\leq k} = \{X \in \mathcal{M} | \operatorname{rank}(X) \leq k\}$$

- $\mathcal{M}$  is  $\mathbb{R}^{m imes n}$  or a submanifold of  $\mathbb{R}^{m imes n}$
- Roughly speaking, a manifold is a set endowed with coordinate patches which overlap smoothly, e.g.,

sphere: 
$$\{x \in \mathbb{R}^n | \|x\|_2 = 1\}.$$



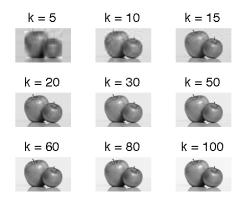
#### Motivations

- E.g. Compression of an image
  - Cost function:  $f(X) = ||X M||_F^2$ , where  $M \in \mathbb{R}^{371 \times 600}$  is the matrix representation of the image



Figure : Size :  $371 \times 600$ 

#### Motivations



#### Figure : Low rank approximation of the image

Rank-constrained Optimization: A Riemannian Approach

Problem: min f(X), s. t.  $X \in \mathcal{M}_{\leq k}$ 

Introduction

A Modified Riemannian Optimization Method An Application Reference

#### Motivations

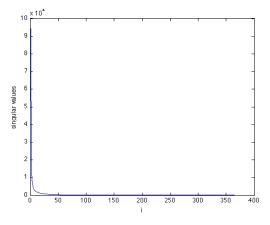


Figure : Singular values of the image

#### Motivations

Rank-constrained optimization problems have appeared in many areas

- $\mathcal{M} = \mathbb{R}^{m \times n}$ 
  - Signal and image processing
  - System identification
  - Computational finance
  - Low-dimensional embedding
- $\mathcal{M} \neq \mathbb{R}^{m \times n}$ 
  - Low-rank approximation of graph similarity matrix
  - Low-rank similarity measure for role model extraction

### Existing Methods

- SVD-based algorithms
- Random multistart-type algorithms, e.g. Alternating Projection method, Double Minimization method , EW-TLS , etc.
- Method of alternating between fixed-rank optimization and a simple update to the rank
- Projected line-search method

### Challenges

- Efficiency (both time and space)
- Rigorous way for rank updating (explain on the next slide)
- Find the rank independent of k
  - Exact solution
  - Approximate solution

#### Framework of Modified Riemannian Optimization Method

- $\mathcal{M}$  is a submanifold of  $\mathbb{R}^{m imes n}$
- In general,  $\mathcal{M}_{\leq k} = \{X \in \mathcal{M} | \mathrm{rank}(X) \leq k\}$  is not a manifold
- $\mathcal{M}_{\leq k} = \mathcal{M}_0 \cup \mathcal{M}_1 \cup \mathcal{M}_2 \cup \cdots \cup \mathcal{M}_k$ , where  $\mathcal{M}_r = \{X \in \mathcal{M} | \operatorname{rank}(X) = r\}$
- Assume  $\mathcal{M}_r$  is a manifold

 $\Rightarrow$  General Riemannian optimization algorithms, e.g., RTR-Newton, can be applied on  $(\mathcal{M}_r, g)$ 

• Question: When and how to move from one fixed-rank manifold to another one?

## When to increase from one fixed-rank manifold to another one?

Consider two functions

$$egin{aligned} &f_{\mathrm{F}}:\mathcal{M} o \mathbb{R}:X\mapsto f_{\mathrm{F}}(X),\ &f_{r}:\mathcal{M}_{r} o \mathbb{R}:X\mapsto f_{r}(X), \end{aligned}$$

such that  $f = f_{\mathrm{F}}|_{\mathcal{M}_{\leq k}}$ ,  $f_r = f|_{\mathcal{M}_r}$ .

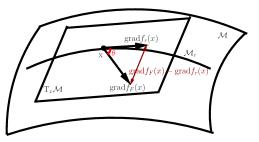
# When to increase from one fixed-rank manifold to another one?

• Condition I (angle threshold,  $\theta_0$ ):

 $\angle(\mathrm{grad} f_\mathrm{F}(X),\mathrm{grad} f_r(X))=\theta>\theta_0$ 

• Condition II (difference threshold,  $\epsilon$ ):

 $\|\operatorname{grad} f_{\operatorname{F}}(X) - \operatorname{grad} f_r(X)\| \geq \epsilon$ 



## How to increase from one fixed-rank manifold to another one?

Line-search method

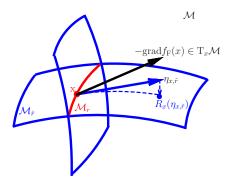
$$X_{i+1}=R_{X_i}(t_i\eta_i),$$

where  $t_i \ge 0$  is a step-size,  $\eta_i$  is a search direction and  $R_{X_i}$  is a retraction, i.e.,  $R_{X_i} : T_{X_i}\mathcal{M} \to \mathcal{M}$  and  $\frac{d}{dt}R_{X_i}(t\eta) = \eta$ 

- How to choose  $\eta_i$ ?  $\rightarrow$  Rank-related Direction Vector
- How to choose retraction  $R? \rightarrow \text{Rank-related Retraction}$

#### Rank-related Objects

- $\eta_{x,\tilde{r}} \in T_x \mathcal{M}_{\leq \tilde{r}}$  and  $\eta_{x,\tilde{r}} \notin T_x \mathcal{M}_{\leq \tilde{r}-1}$  is a rank- $\tilde{r}$ -related direction vector
- $\eta_{x,\tilde{r}} \in \operatorname{argmin}_{\eta \in \mathrm{T}_{x}\mathcal{M}_{\leq \tilde{r}}} \|-\operatorname{grad} f_{\mathrm{F}}(x) \eta\|_{F}$
- Rank-related retraction  $\tilde{R}_x$  satisfies  $\tilde{R}_x(t\eta_{x,\tilde{r}}) \in \mathcal{M}_{\tilde{r}}, \forall t \in (0, \delta)$



#### Rank Reduction

- $\bullet$  Truncate rank and retract to  ${\cal M}$
- May increase the function value
- Do not destroy the progress that is made in the previous rank increasing step, i.e.,

$$f(X_{i+1}) - f(X_s) \le c(f(X_{s+1}) - f(X_s)),$$

where s is such that the latest rank increase was from  $X_s$  to  $X_{s+1}$ , 0 < c < 1.

#### Main Theoretical Results

- Parameter  $\epsilon$  is used to adjust the accuracy of the approximate solutions.
- (Global Convergence) Suppose some reasonable assumptions hold. Then the sequence {X<sub>i</sub>} generated by modified Riemannian Optimization method satisfies

$$\lim \inf_{i\to\infty} \|P_{\mathrm{T}_{X_i}\mathcal{M}_{\leq k}}(\mathrm{grad} f_{\mathcal{F}}(X_i))\| \leq \left(\sqrt{1+\frac{1}{\tan(\theta_0)^2}}\right)\epsilon.$$

### Weighted Low-rank Approximation

Problem Formulation

$$\underset{X \in \mathcal{M}_{\leq k}}{\operatorname{argmin}} \|B - X\|_{W}^{2}, \ \|B - X\|_{W}^{2} = \operatorname{vec}\{B - X\}^{T} W\operatorname{vec}\{B - X\}$$

- $\mathcal{M} = \mathbb{R}^{m \times n}$
- $B \in \mathbb{R}^{m \times n}$  is a given data matrix
- $W \in \mathbb{R}^{mn \times mn}$  is a positive definite symmetric weighting matrix
- $vec{A}$  denotes the vectorized form of A

#### Experiment

Comparison of different methods.

- The data matrix  $B = B_1 B_2^T$  is a random generated  $80 \times 10$  matrix with rank 5,  $B_1 \in \mathbb{R}^{80 \times 5}, B_2 \in \mathbb{R}^{10 \times 5}$ .
- The weighting matrix  $W \in \mathbb{R}^{800 \times 800}$  is a positive definite symmetric matrix.
- k = 3, 5, 7.

#### Experiment

Four algorithms are compared.

- MROM: modified Riemannian optimization method
- SULS: Projected line-search method (Schneider and Uschmajew [SU14])
- DMM: Double minimization method (Brace and Manton [BM06])
- APM: Alternating projections method (Lu et. al [LPW97] or Wentzell et. al [WAK97])

#### Experiment

k	method	rank	f	Rel Err $\left(\frac{\ A-X\ _W}{\ A\ _W}\right)$	t
k = 3	MROM	3	$8.846_{+01}$	3.513_01	4.823_01
	SULS	3	$8.846_{+01}$	$3.513_{-01}$	$2.190_{+00}$
	DMM	3	$8.846_{+01}$	$3.513_{-01}$	$4.706_{+00}$
	APM	3	$8.846_{+01}$	$3.513_{-01}$	$5.000_{+00}$
k = 5	MROM	5	$2.191_{-19}$	$1.557_{-11}$	6.890_01
	SULS	5	$2.147_{-12}$	$4.874_{-08}$	$1.045_{+00}$
	DMM	5	$1.606_{-15}$	$1.324_{-09}$	$4.351_{+00}$
	APM	5	$7.611_{-09}$	$2.895_{-06}$	$3.585_{+00}$
k = 7	MROM	5	$1.799_{-21}$	$1.346_{-12}$	4.730_01
	SULS	7(0/100)	$1.401_{-12}$	3.780 <sub>-08</sub>	$2.316_{+00}$
	DMM	5	$1.915_{-18}$	$4.407_{-11}$	$2.182_{+00}$
	APM	7(0/100)	$2.349_{-10}$	$4.865_{-07}$	$7.002_{\pm 00}$

Table : The number in the parenthesis indicates the fraction of experiments where the numerical rank (number of singular values greater than  $10^{-8}$ ) found by the algorithm equals the true rank. The subscript  $\pm k$  indicates a scale of  $10^{\pm k}$ .

### Conclusion

$$\min_{X\in\mathcal{M}_{\leq k}} f(X)$$

- Generalize the admissible set from  $\mathbb{R}^{m \times n}_{\leq k}$  to  $\mathcal{M}_{\leq k}$ ;
- Define an algorithm solving a rank inequality constrained problem while finding a suitable rank for approximation;
- Prove theoretical convergence results;



## Thank you for your attention!

Rank-constrained Optimization: A Riemannian Approach

Problem: min f(X), s. t.  $X \in \mathcal{M}_{\leq k}$ 

#### Reference



#### I. Brace and J. H. Manton.

An improved BFGS-on-manifold algorithm for computing low-rank weighted approximations. In Proceedings of 17th International Symposium on Mathematical Theory of Networks and Systems, pages 1735–1738, 2006.



#### W.-S. Lu, S.-C. Pei, and P.-H. Wang.

Weighted low-rank approximation of general complex matrices and its application in the design of 2-d digital filters.

IEEE Transactions on Circuits and SystemsI, 44:650-655, 1997.



#### R. Schneider and A. Uschmajew.

Convergence results for projected line-search methods on varieties of low-rank matrices via  $\{\L\}$  ojasiewicz inequality.

ArXiv e-prints, pages -1-1, feb 2014.



Peter D. Wentzell, Darren T. Andrews, and Bruce R. Kowalski.

Maximum likelihood multivariate calibration. Analytical Chemistry, 69(13):2299–2311, 1997.